## Move Instructions

Move instructions move data between registers.

## Unconditional move instructions

mov instruction has two formats:

| mov | s_reg, d_reg | mov |
| :--- | :--- | :--- | | $\$ T 0, \$ T 1$ |
| :--- |
| mov |
| value, d_reg |$\quad \operatorname{mov} 2, \$ T 0$

$\mathrm{T} 0=1$ then mov $\$ \mathrm{~T} 0, \$ \mathrm{~T} 1$ results $\$ \mathrm{~T} 1=1$

## Conditional move instructions

cmovXY can have two or three operands. The first operand must be a register. The instruction is only executed if the value of the first operand satisfies the condition specified by the instruction. XY can be as below:
eq The instruction is executed if the first operand is equal to zero.
ne The instruction is executed if the first operand is not equal to zero.
It The instruction is executed if the first operand is less than zero.
le The instruction is executed if the first operand is less than or equal to zero.
gt The instruction is executed if the first operand is greater than zero.
ge The instruction is executed if the first operand is greater than or equal to zero.

The format of the conditional move instruction with three operands is as below:
cmovXY s_reg1, s_reg2, d_reg cmovXY \$T0, \$T1, \$T2 cmovXY s_reg, vālue, d_reg cmovXY \$T0, 2, \$T1

Cmovne \$T0, \$T1, \$T2

- Where $\mathrm{T} 0=0 \times 02$ and $\mathrm{T} 1=3$ executed $\mathrm{T} 2=3$
- Where $\mathrm{T} 0=0 \mathrm{x} 03$ and $\mathrm{T} 1=3$ not executed, T 2 unchanged

Cmovle $\quad \$ \mathrm{~T} 0,3, \$ \mathrm{~T} 1$

- Where $\mathrm{T} 0=0 \mathrm{xf}$...f executed $\mathrm{T} 1=3$
- Where T0 $=0 \times 4$ not executed T 1 unchanged
- Where $\mathrm{T} 0=0$ executed $\mathrm{T} 1=3$

The format of the conditional move instruction with two operands is as follow:
cmovXY d_reg/s_reg1, s_reg2 cmovXY \$T0, \$T1
cmovXY d_reg/s_reg, value cmovXY \$T0, 2

- The destination register is the first one.

Cmovge \$T0, \$T1

- where $\mathrm{T} 0=0 \mathrm{x} 02$ and $\mathrm{T} 1=2$ executed $\mathrm{T} 0=2$
- where $\mathrm{T} 0=0 \mathrm{xf} . . . \mathrm{f}$ and $\mathrm{T} 1=2$ not executed, T 0 unchanged

Cmovlt \$T0, 3

- where $\mathrm{T} 0=0 x f$...f executed $\mathrm{T} 0=3$
- where $\mathrm{T} 0=0 \mathrm{x} 4$ not executed $\mathrm{T} 0=0 \mathrm{x} 4$


## More Arithmetic Instructions

clr instruction sets the value of a register to 0, e.g. clr $\$ T 0$ Only one operand
Can be done with mov $\#$ mov $0, \$$ T0
$a \mathrm{~b} s \mathrm{q}$ instruction calculates the absolute value of a quadword. For example:

```
absq-0x123, $T0 $T0 = |-0x123|
```

$\mathrm{T} 0=123$

```
absq$T0 $T0 = | $T0 |
If $TO is -123, T0 will be 123
```

```
absq$T0, $T1 $T1 = | $T0|
```

If T0 is -123 , T 1 will be 123 , T 0 unchanged
negq instruction negates the contents of an operand. For example:
negq 0x123, \$T0 \$T0 = - 0x123
negq\$T0 \$T0 = -\$T0
negq\$T0, \$T1 \$T1 = - \$T0

Example: What are the contents of the registers after the execution of the program below? The content of each of the registers should be written as a quadword.

```
•
.
code{
```

        mov 10, \$T0
        mov -2, \$T1
        mov \$T0, \$T2
        cmovle \(\$ T 0,2\)
        cmovgt \$T2, \$T1, \$T3
        cmovne \$T1, -5
        \}
    .
-

Answer:

| mov | 10, \$T0 | \# T0 $=10$ | $\mathrm{T} 0=0 \mathrm{x} 000000000000000 \mathrm{a}$ |
| :---: | :---: | :---: | :---: |
| mov | -2, \$T1 | \# T1 $=-2$ | T1 $=0 x f f f f f f f f f f f f f f f e$ |
| mov | \$T0, \$T2 | \# T2 $=10$ | $\mathrm{T} 2=0 \mathrm{x} 000000000000000 \mathrm{a}$ |
| cmovle | \$T0, 2 | \# not exec | uted |
| cmovgt | \$T2, \$T1, \$T | \# T3 | $=-2 \quad \mathrm{~T} 3=0 \mathrm{xfffffffffffffffe}$ |
| cmovne | \$T1, -5 | \# T1 $=-5$ | T1 $=0 x f f f f f f f f f f f f f f f b$ |

## Another example

There are no integer division instructions in Alpha.
You may implement integer division using addition and subtraction statements.

```
void main () {
    int quotient, remainder, divider=3, dividend=10;
    quotient = 0;
    remainder = dividend;
    while (remainder >= divider) {
        quotient++;
        remainder = remainder - divider;
    }
}
```

Convert the above C program to an assembly program. It should be assumed that (a) each variable is a quadword, (b) dividend is stored in $\$ \mathrm{SO}$, (c) divider is stored in \$S1, (d) quotient is in \$S2 and (e) remainder is in $\$$ S3. The converted program should have the same control structure as the C program.

```
.
•
code{
\begin{tabular}{cccc} 
mov & \(10, \$ S 0\) & \(/ / \$ S 0\) is dividend \\
mov & \(3, \$ S 1\) & \(/ / \$ S 1\) is divider \\
mov & \(0, \$ S 2\) & \(/ / \$ S 2\) is quotient \\
mov & \(\$ S 0, \$ S 3\) & \(/ / \$ S 3\) is remainder \\
check: & cmple & \(\$ S 1, \$ S 3, \$ T 0 / /\) check whether \\
divider \(<=\) remainder & & \\
beq & \(\$ T 0\), stop & \\
& addq & \(\$ S 2,1\) &
\end{tabular}
```

