

Lower Bound for Sorting Complexity

• **Theorem 2.30**: Any algorithm that sorts by comparing only pairs of elements must use at least

 $\lceil \log_2(n!) \rceil \cong n \log_2 n - 1.44n$

comparisons in the worst case (that is, for some "worst" input sequence) and in the average case

- Stirling's approximation of the factorial (n!):

$$1 \cdot 2 \cdot \dots \cdot n \equiv n! \geq \left(\frac{n}{e}\right)^n \sqrt{2\pi n} \approx 2.5 n^{n+0.5} e^{-n}$$





Decision Tree for Sorting *n* Items



Decision tree for n = 3:

- *i*:*j* a comparison of
 a_i and *a_j*
- ijk a sorted array $(a_i a_j a_k)$
- *n*! permutations ⇒
 n! leaves

Sorting in descending order of the numbers

Lecture 9

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Decision Tree for Sorting *n* Items

- Decision tree for n = 3: an array $A = \{a_1, a_2, a_3\}$
- Example: { a_1 =35, a_2 =10, a_3 =17}
 - Comparison 1:2 $(35 > 10) \rightarrow$ left branch $a_1 > a_2$
 - Comparison 2:3 $(10 < 17) \rightarrow \text{right branch } a_2 < a_3$
 - Comparison 1:3 $(35 > 17) \rightarrow$ left branch $a_1 > a_3$
- Sorted array $132 \rightarrow \{a_1=35, a_3=17, a_2=10\}$





Decision Tree

Lemma: Decision tree of height *h* has $L_h \le 2^h$ leaves **Proof** by mathematical induction:

· h = 1: any tree of height 1 has $L_1 \le 2^1$ leaves

$$h-1 \rightarrow h$$
:

- · Let any tree of height h 1 have $L_{h-1} \le 2^{h-1}$ leaves
- · Any tree of height h consists of a root and two subtrees of height at most h 1
- $\cdot \text{ Therefore, } L_h = L_{h-1} + L_{h-1} \leq 2^{h-1} + 2^{h-1} = 2^h$





Worst-Case Complexity of Sorting

- **Theorem 2.32**: The worst-case complexity of sorting *n* items by pairwise comparisons is $\Omega(n \log n)$
- **Proof**:
 - Any decision tree of height h has at most 2^h leaves (see Lemma, Slide 4)
 - The least height *h* such that $L_h = 2^h \ge n!$ leaves is $h \ge \log_2(n!) \cong n \log_2 n - 1.44 n$





Bucket Sort (Exercise 2.6.2)

Let all integers to sort in an array *a* of size *n* be in the **fixed range** $[1, ..., q_{max}]$

- 1. Introduce a counter array *t* of size q_{\max} and set its entries initially to zero
- 2. Scan through *a* to accumulate in the counters t[i]; $i = 0, ..., q_{max} - 1$, how many times each item i + 1is found in *a*
- 3. Loop through $0 \le i \le q_{\max} 1$ and output t[i] copies of integer i + 1 at each step





Bucket Sort (Exercise 2.6.2)

Worst- and average-case time complexity of bucket sort is $\Theta(n)$ provided that q_{\max} is fixed

- $q_{\text{max}} + n$ elementary operations to first set *t* to zero and then count how many times t[i] each item i + 1 is found in *a*
- $q_{\text{max}} + n$ elementary operations to successively output the sorted array *a* by repeating *t*[*i*] times each entry *i* + 1

Theorem 2.30 does not hold under additional constraints!





Data Search: Efficiency

- Data record <> Specific key
- Goal: to find all records with keys matching a given search key
- Purpose:
 - to access information in the record for processing, or
 - to update information in the record, or
 - to insert a new record or to delete the record





Types of Search

- Static search: unalterable databases
 - Given a data structure *D* of records and a search key *k*, either return the record associated with *k* in *D* or indicate that *k* is not found, without altering *D*
 - If *k* occurs more than once, return any occurrence
 - **Examples**: searching a phone directory or a dictionary
- Dynamic search: alterable databases
 - Records may be inserted or removed





Static Sequential Search (SSS)

- Lemma 3.3: Both successful and unsuccessful SSS have worst- and average-case complexity $\Theta(n)$
 - **Proof**: the unsuccessful search explores each of *n* keys, so the worst- and average-case time is $\Theta(n)$; the successful search examines *n* keys in the worst case and n/2 on the average, which is still $\Theta(n)$
 - Sequential search is the only option for an unsorted array and for linked-list data structures of records







Static Binary Search *O*(log *n*)

- Ordered array: $\mathbf{key}_0 < \mathbf{key}_1 < \dots < \mathbf{key}_{n-1}$
- Compare the search **key** with the record **key**_{*i*} at the middle position $i = \lfloor (n-1)/2 \rfloor$
 - if $\mathbf{key} = \mathbf{key}_i$, return *i*
 - if key < key_i or key < key_i, then it must be in the 1st or in the 2nd half of the array, respectively
- Apply the previous two steps to the chosen half of the array iteratively (repeating halving principle)





Pseudocode of Binary Search

begin BinarySearch (an integer array *a* of size *n*, a search key) low $\leftarrow 0$; high $\leftarrow n - 1$ while low ≤ high do middle \leftarrow | (low + high) / 2 | if a [middle] < key then low \leftarrow middle + 1 else if a middle > key then high \leftarrow middle -1else return middle end if end while return ItemNotFound end BinarySearch







Lecture 9









Worst-Case Complexity Θ(log n) of Binary Search

- Let $n = 2^k 1$; k = 1, 2, ..., then the binary tree is complete (each internal node has 2 children)
 - The tree height is k 1 since the tree is **balanced**
 - Each tree level *l* contains 2^l nodes for l = 0 (the root), 1, ..., k 2, k 1 (the leaves)
- l+1 comparisons to find a key of level l
- The worst case: $k = \log_2(n + 1)$ comparisons so that the time complexity is $\Theta(\log n)$





Average-Case Complexity $\Theta(\log n)$ of Binary Search

Lemma 3.9: The average-case complexity of binary search in a balanced binary tree is $\Theta(\log n)$

Proof: $k = \lceil \log_2(n + 1) \rceil - 1$ is the depth of the tree

At least half of the nodes in the tree have the depth at least k - 1

The average depth over all nodes is at least k/2which is $\Omega(\log n)$

Expected search time for an arbitrary binary search tree is equal to the average tree height $\Theta(\log n)$





Interpolation Search

- Improvement of binary search if it is possible to guess where the desired key sits
 - **Example**: the search for C or X in a phone directory
 - Practical if the sorted keys are almost uniformly distributed over their range
- BS: the middle position $m = \left|\frac{l+r}{2}\right| = l + \left[0.5(r-l)\right]$
- IS: the predicted position

$$m = l + \left\lceil \rho(r-l) \right\rceil \equiv l + \left\lfloor \frac{k - A[l]}{A[r] - A[l]}(r-l) \right\rfloor$$





Dynamic Binary Tree Search

- Static binary search is converted into a dynamic binary tree search by allowing for insertion and deletion of data records
- Binary tree search makes actual use of the binary search tree data structure
 - The data structure is constructed by linking data records
 - Any node of a binary search tree may be removed

