## Symbol Table and Hashing

- (Symbol) table is a set of table entries, $(k, v)$
- Each entry contains:
- a unique key, $k$, and
- a value (information), $v$
- Each key uniquely identifies its entry
- Table searching:
- Given: a search key, $k$
- Find: the table entry, $(k, v)$

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## Symbol Table and Hashing

- Once the entry $(k, v)$ is found:
- its value $v$, may be updated,
- it may be retrieved, or
- the entire entry, ( $k, v$ ), may be removed from the table
- If no entry with key $k$ exists in the table:
- a new entry with $k$ as its key may be inserted to the table
- Hashing:
- a technique of storing values in the tables and
- searching for them in linear, $O(n)$, worst-case and extremely fast, $O(1)$, average-case time
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## Basic Features of Hashing

- Hashing computes an integer, called the hash code, for each object
- The computation is called the hash function, $h(k)$
- It maps objects (e.g., keys $k$ ) to the array indices (e.g., 0,1 , ..., $i_{\text {max }}$ )
- An object with a key $k$ has to be stored at location $h(k)$
- The hash function must always return a valid index for the array

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## Basic Features of Hashing

- Perfect hash function $\rightarrow$ a different index value for every key. But such a function cannot be always found.
- Collision: if two distinct keys, $k_{1} \neq k_{2}$, map to the same table address, $h\left(k_{1}\right)=h\left(k_{2}\right)$
- Collision resolution policy: how to find additional storage to store one of the collided table entries
- Load factor $\lambda$ - fraction of the already occupied entries ( $m$ occupied entries in the table of size $n \rightarrow \lambda=m / n$ )

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## How Common Are Collisions?

- Von Mises Birthday Paradox:
if there are more than 23 people in a room, the chance is greater than $50 \%$ (!) that two or more of them will have the same birthday
- In the only $6.3 \%$ full table (since $23 / 365=0.063$ ) there is better than $50 \%$ chance of a collision!
- Therefore: $50 \%$ chance of collision if $\lambda=0.063$

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## How Common Are Collisions?

- Probability $\mathrm{Q}_{N}(n)$ of no collision:
- that is, that none of the $n$ items collides, being randomly tossed into a table with $N$ slots:
$\mathrm{Q}_{N}(1)=1 \equiv \frac{N}{N} ; \quad \mathrm{Q}_{N}(2)=\mathrm{Q}_{N}(1) \frac{N-1}{N} \equiv \frac{N(N-1)}{N^{2}} ;$
$\mathrm{Q}_{N}(3)=\mathrm{Q}_{N}(2) \frac{N-2}{N} \equiv \frac{N(N-1)(N-2)}{N^{3}} ;$
$\mathrm{Q}_{N}(n)=\mathrm{Q}_{N}(n-1) \frac{N-n+1}{N} \equiv \frac{N(N-1) \ldots(N-n+1)}{N^{n}}$
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## Open Addressing with Linear Probing (OALP)

- The simplest collision resolution policy:
- Successive search for the first empty entry at a lower location
- If no such entry, then "wrap around" the table
- Lemma 3.33: The average number of probes for successful, $T_{\mathrm{ss}}(\lambda)$, and unsuccessful, $T_{\mathrm{us}}(\lambda)$, search in a hash table with load factor $\lambda=m / n$ is, respectively,
$T_{\mathrm{ss}}(\lambda)=0.5\left(1+\frac{1}{1-\lambda}\right)$ and $T_{\mathrm{us}}(\lambda)=0.5\left(1+\left(\frac{1}{1-\lambda}\right)^{2}\right)$
- Drawbacks: clustering of keys in the table

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## Open Addressing with Double Hashing (OADH)

- Better collision resolution policy reducing the clustering:
- hash the collided key again with a different hash function
- use the result of the second hashing as an increment for probing table locations (including wraparound)
- Lemma 3.35: Assuming that OADH provides nearly uniform hashing, the average number of probes for successful, $T_{\text {ss }}(\lambda)$, and unsuccessful, $T_{\text {us }}(\lambda)$, search is, respectively, $T_{\mathrm{ss}}(\lambda)=\frac{1}{\lambda} \ln \left(\frac{1}{1-\lambda}\right)$ and $T_{\mathrm{us}}(\lambda)=\frac{1}{1-\lambda}$

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## Two More Collision Resolution Techniques

- Open addressing has a problem if significant number of items need to be deleted:
- Logically deleted items must remain in the table until the table can be re-organised
- Two techniques to attenuate this drawback:
- Chaining
- Hash bucket


## Chaining and Hash Bucket

- Chaining: all keys collided at a single hash address are placed on a linked list, or chain, started at that address
- Hash bucket: a big hash table is divided into a number of small sub-tables, or buckets
- the hush function maps a key into one of the buckets
- the keys are stored in each bucket sequentially in increasing order

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## Choosing a hash function

- Four basic methods:
- division, folding, middle-squaring, and truncation
- Division:
- choose a prime number as the table size $n$
- convert keys, $k$, into integers
- use the remainder $h(k)=k \bmod n$ as a hash value of $k$
- get the double hashing decrement using the quotient $\Delta k=\max \{1,(k / n) \bmod n\}$


## Choosing a hash function

## - Folding:

- divide the integer key, $k$, into sections
- add, subtract, and / or multiply them together for combining into the final value, $h(k)$
Ex.: $k=013402122 \rightarrow 013,402,122 \rightarrow h(k)=013+402+122=537$
- Middle-squaring:
- choose a middle section of the integer key, $k$
- square the chosen section
- use a middle section of the result as $h(k)$

Ex.: $k=013402122 \rightarrow$ mid: $402 \rightarrow 402^{2}=161404 \rightarrow$ mid: $h(k)=6140$

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## Choosing a hash function

## Truncation:

- delete part of the key, $k$
- use the remaining digits (bits, characters) as $h(k)$

Example:
$k=013402122 \rightarrow$ last 3 digits: $h(k)=122$

- Notice that truncation does not spread keys uniformly into the table; thus it is often used in conjunction with other methods


## Efficiency of Search in Hash Tables

Load factor $\lambda$ : if a table of size $n$ has exactly $m$ occupied entries, then $\ddot{e}=m / n$

- Average numbers of probe addresses examined for a successful ( $T_{\text {ss }}(\lambda)$ ) and unsuccessful $\left(T_{\text {us }}(\lambda)\right)$ search:

|  | OALP: $\lambda<0.7$ | OADH: $\lambda<0.7$ | SC |
| :---: | :---: | :---: | :---: |
| $T_{\text {ss }}(\lambda)$ | $0.5(1+1 /(1-\lambda))$ | $(1 / \lambda) \ln (1 /(1-\lambda))$ | $1+\lambda / 2$ |
| $T_{\text {us }}(\lambda)$ | $0.5\left(1+(1 /(1-\lambda))^{2}\right)$ | $1 /(1-\lambda)$ | $\lambda$ |
| SC - separate chaining; $\lambda$ may be higher than 1 |  |  |  |

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Table Data Type Representations: Comparative Performance

| Operation | Representation |  |  |
| :--- | :---: | :---: | :---: |
|  | Sorted array | AVL tree | Hash table |
| Initialize | $O(n)$ | $O(1)$ | $O(n)$ |
| Is full? | $O(1)$ | $O(1)$ | $O(1)$ |
| Search*) | $O(\log n)$ | $O(\log n)$ | $O(1)$ |
| Insert | $O(n)$ | $O(\log n)$ | $O(1)$ |
| Delete | $O(n)$ | $O(\log n)$ | $O(1)$ |
| Enumerate | $O(n)$ | $O(n)$ | $O(n \log n)^{* *)}$ |

${ }^{*}$ ) also: Retrieve, Update **)To enumerate a hash table, entries must first be sorted in ascending order of keys that takes $O(n \log n)$ time Lecture 11 COMPSCI 220 - AP G. Gimelfarb


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