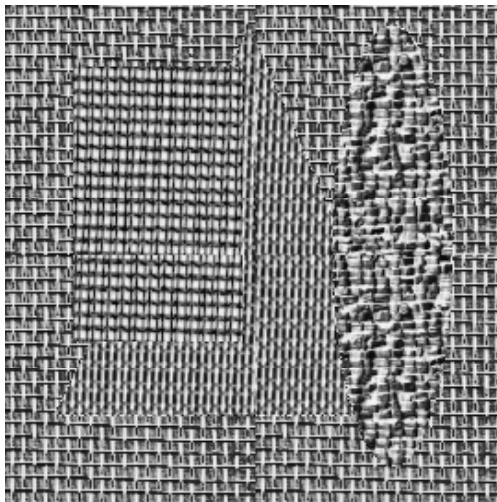


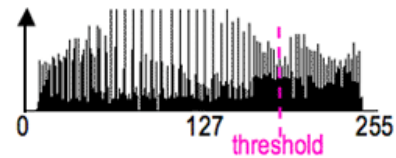


# Texture Segmentation

- Grey level or colour pixel values by themselves are not sufficient for segmenting natural highly-textured images:



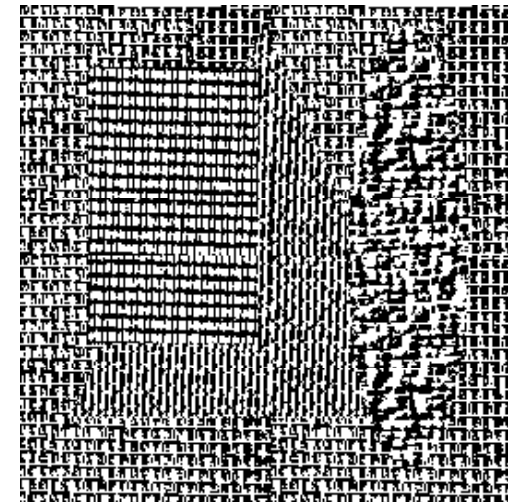
Collage of various textures



Grey level histogram



Segmentation by thresholding

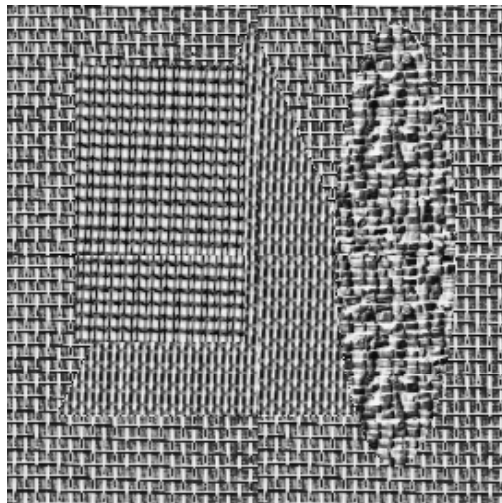


Meaningless regions obtained by simple thresholding



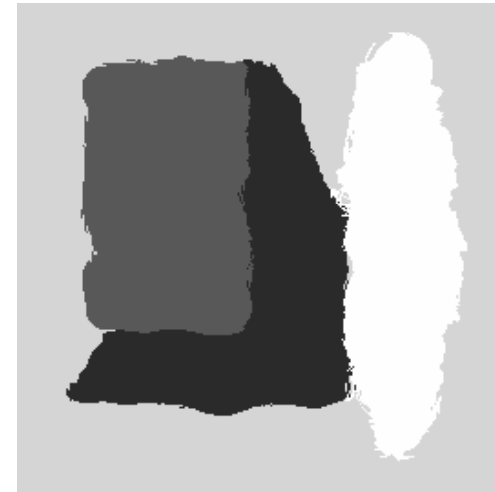
# Texture Segmentation

- Specific texture measures (features) describing local spatial signal patterns have to be used



Collage of various textures

Segmentation by  
separation of local  
signal features



Meaningful texture

From: <http://www.sztaki.hu/~sziranyi/textu-iu.html>



# Texture Segmentation



From: [http://www.ercim.org/publication/Ercim\\_News/enw64/mikes.html](http://www.ercim.org/publication/Ercim_News/enw64/mikes.html)

- Texture is a spatial property that characterises groups of pixels
- A local measure of texture is computed over a pixel neighbourhood



## Variance as a Texture Feature

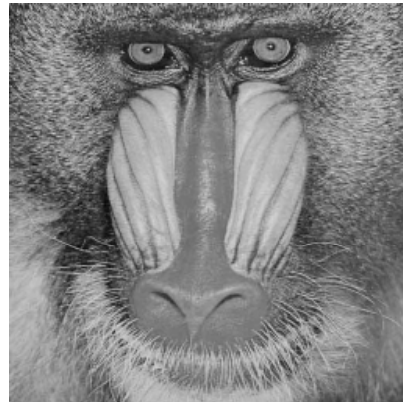
- The simplest statistical measure is the *variance*  $\sigma^2$  of grey levels in a square  $n \times n$  neighbourhood centred on a pixel:

$$\sigma^2 = \frac{1}{n^2} \sum_{\xi=-n/2}^{n/2} \sum_{\eta=-n/2}^{n/2} (f(x+\xi, y+\eta) - \mu)^2; \quad \mu = \frac{1}{n^2} \sum_{\xi=-n/2}^{n/2} \sum_{\eta=-n/2}^{n/2} f(x+\xi, y+\eta)$$

- **“Variance” image:** scaled standard deviations  $\sigma$  for each pixel
  - Bright regions in the variance image: high local variance of grey levels
- For most of simple statistical measures are of little use
- If two textures of interest are periodic, they might be separated in the frequency domain by comparing the spectra of small samples taken from the two patterns



# Variance as a Texture Feature

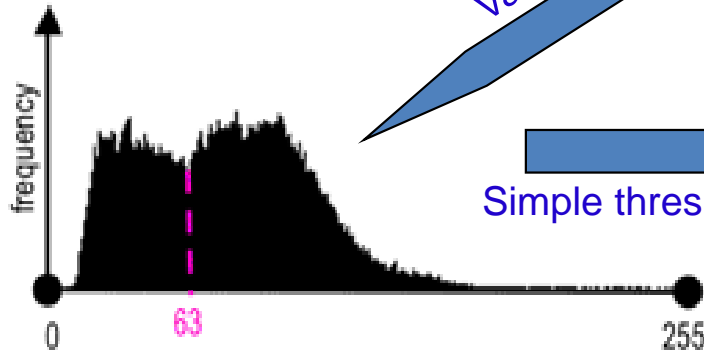
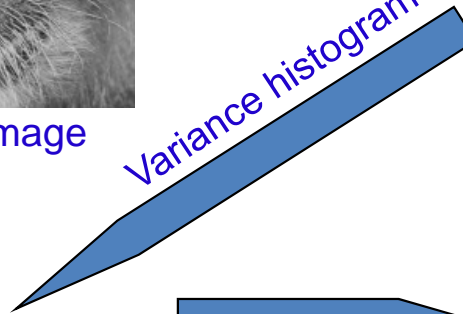


Greyscale image

Variance image



Variance histogram



Simple thresholding





# Image Segmentation for Skin Detection: Colour predicate



# Colour Segmentation

- Region-of-interest in a training image - look-up table of skin colours
  - **Drawback:** incorrect classification of skin pixels absent in the training sample and background pixels
- Edge-based segmentation - regions with closed boundaries formed by edge strokes



# Colour Predicate

- The use of many training images
- Automatic segmentation of each training image into skin and background regions
- Can use any colour space (RGB, rgb, YCrCb, HSI, YCM)
- RGB non discriminative for skin
- Look at Hue images
  - Thresholding the hue images





# Logarithmic hue

- CCD micro-camera
  - poor results with angular transform (classic *HIS*)
- **Logarithmic hue** difference between **Green** and **Red**
  - independence from lighting conditions
  - **Logarithmic hue** values: R - G components only because red prevails in skin; the ratio G/R is robust to intensity changes:

$$H = 256 \frac{G}{R} \text{ if } G < R \text{ and } H = 255 \text{ if } G \geq R$$



Intensity I

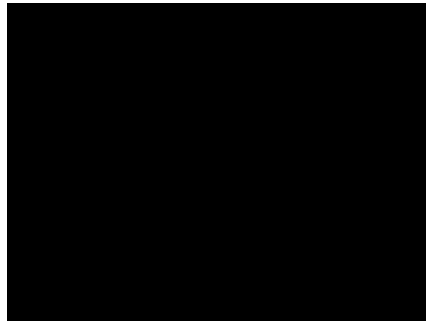
Hue H

3/03/2011

COMSP 773S1C



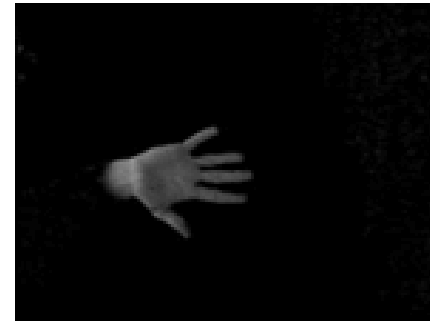
# Segmentation with Different Ranges of the Hue



0 - 100



0 - 150



80 - 190



100 - 255



150 - 255

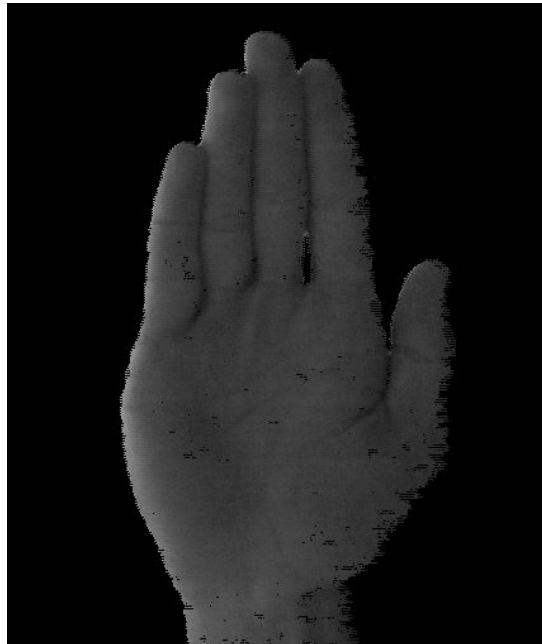


200 - 255



# Hue Thresholding

- Raw hue-based segmentation



7/03/2011

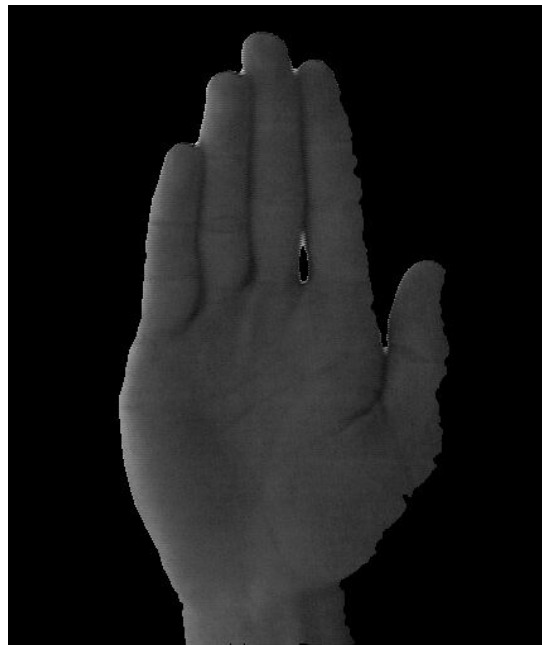
COMSPCI 773S1C

61



# Post-processing

- morphological opening + median filtering



7/03/2011

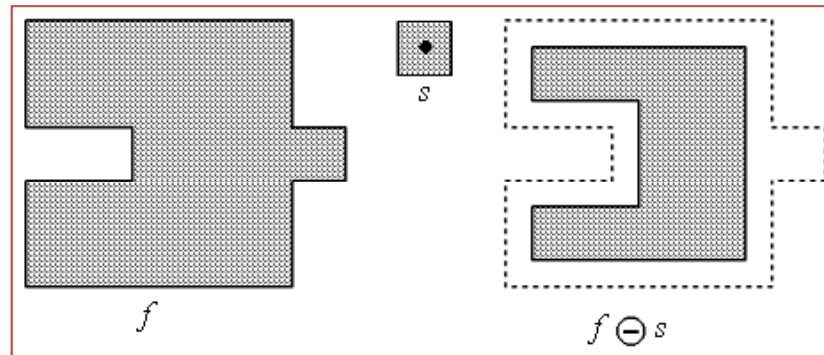
COMSPCI 773S1C

62



## Fundamental Operation: Erosion

- **Erosion**  $f \ominus s$  of a binary image  $f$  by a structuring element  $s$  produces a new binary image  $g = f \ominus s$ 
  - The eroded image has ones in all locations  $(x,y)$  of an origin of the structuring element  $s$  at which  $s$  **fits** the input image  $f$ 
    - For all pixel coordinates  $(x,y)$ ,  $g(x,y) = 1$  if  $s$  fits  $f$  and 0 otherwise

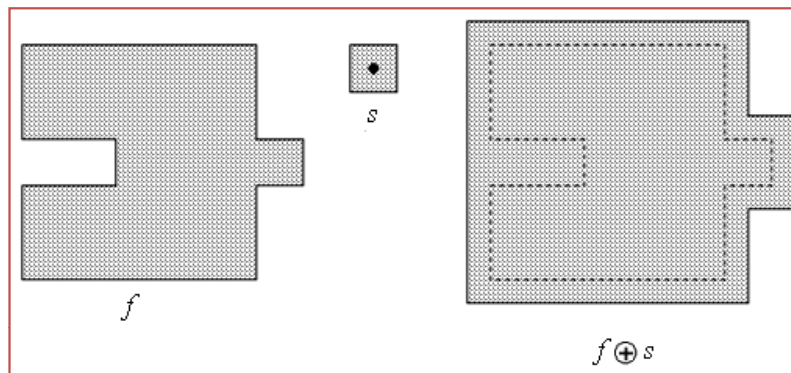


From: <http://www.inf.u-szeged.hu/~ssip/1996/morpho/morphology.html>



## Fundamental Operation: Dilation

- **Dilation**  $f \oplus s$  of a binary image  $f$  by a structuring element  $s$  produces a new binary image  $g = f \oplus s$ 
  - The dilated image has ones in all locations  $(x,y)$  of an origin of the structuring element  $s$  at which  $s$  **hits** the input image  $f$ 
    - For all pixel coordinates  $(x,y)$ ,  $g(x,y) = 1$  if  $s$  hits  $f$  and 0 otherwise



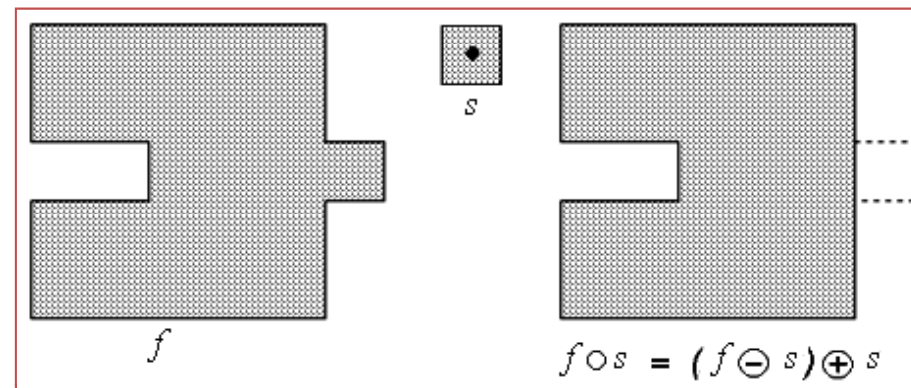
From: <http://www.inf.u-szeged.hu/~ssip/1996/morpho/morphology.html>



# Opening

- **Opening**  $f \circ s$  of an image  $f$  by a structuring element  $s$  is an *erosion* followed by a *dilation*:

$$f \circ s = (f \ominus s) \oplus s$$



From: <http://www.inf.u-szeged.hu/~ssip/1996/morpho/morphology.html>



# Median filter



0	0	0	30	30	30
0	0	0	30	30	30
0	0	0	30	30	30
10	10	10	20	20	20
10	10	10	20	20	20
10	10	10	20	20	20

	0	0	30	30	
	0	10	30	30	
	10	10	20	20	
	10	10	20	20	

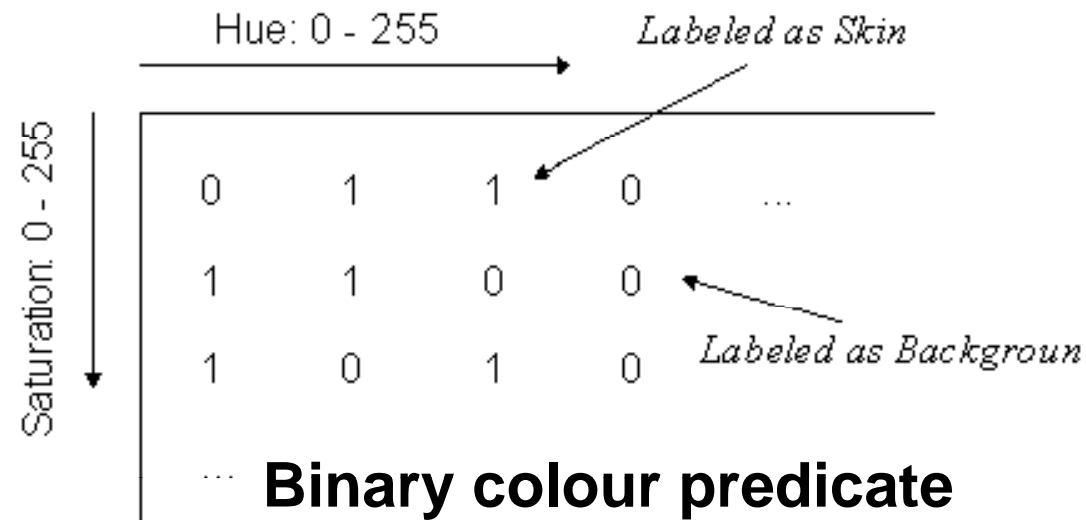
The median is calculated by first sorting all the pixel values from the window into numerical order, and then replacing the pixel being considered with the middle (median) pixel value.

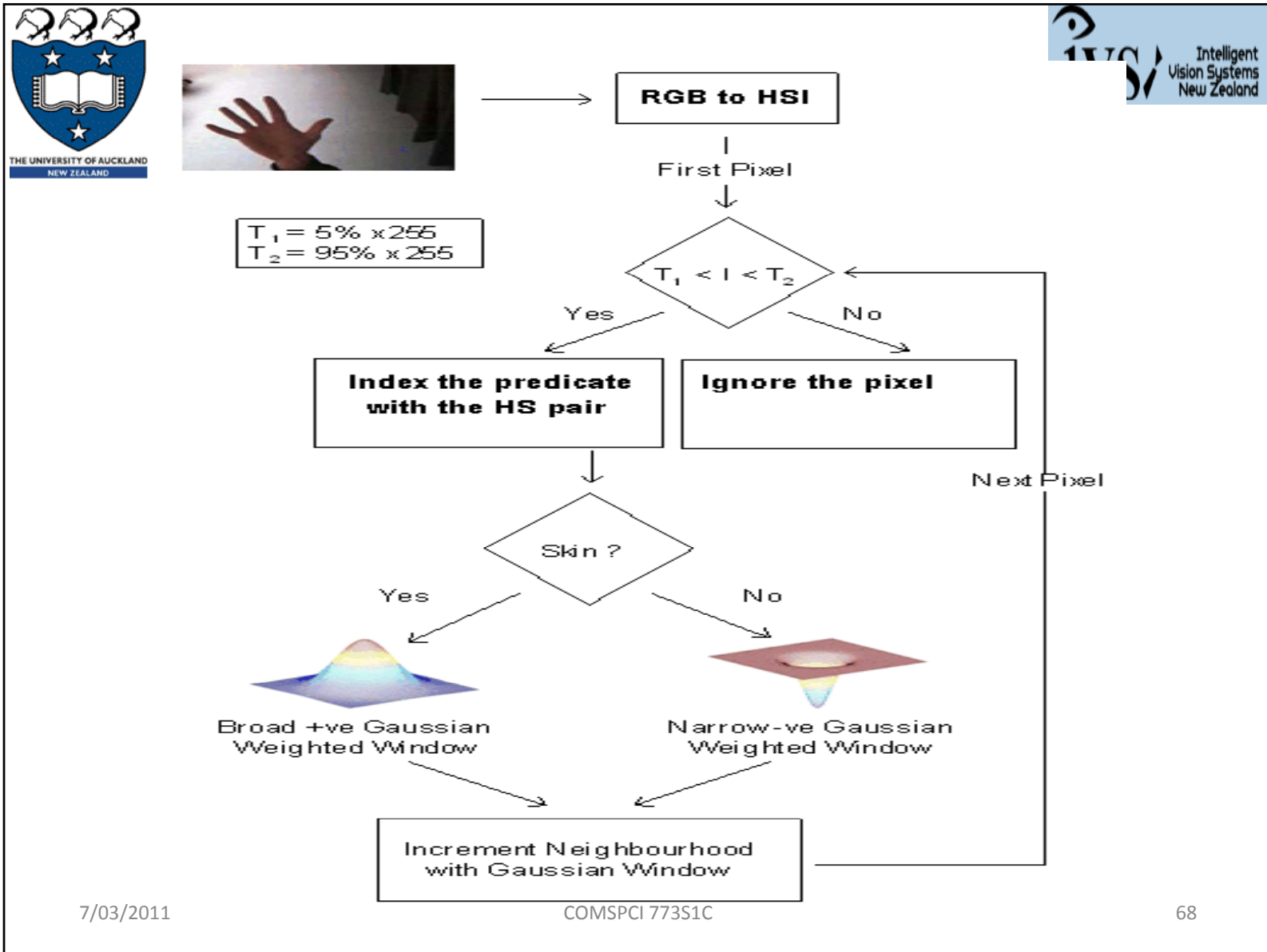




# Predicate Training

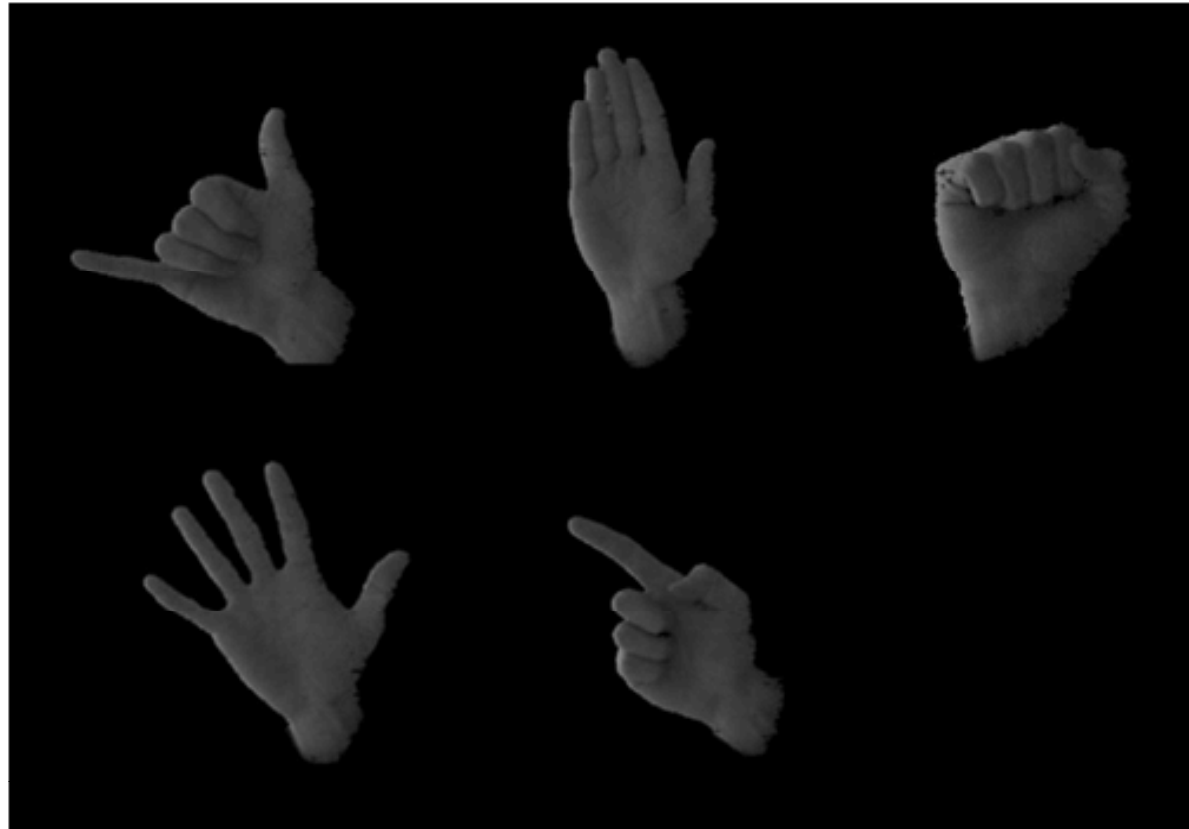
- Largest connected region of skin-coloured pixels: connected component algorithm of Haralick-Shapiro







# The Use of the Predicate



7/03/2011

COMSPCI 773S1C

69