

$$P = RTS$$

$${}^2P_1 = P_1 P_1$$

$$R = \begin{pmatrix} \cos\theta & -\sin\theta & 0 \\ \sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$T = \begin{pmatrix} 1 & 0 & t_x \\ 0 & 1 & t_y \\ 0 & 0 & 1 \end{pmatrix}$$

$$S = \begin{pmatrix} S_x & 0 & 0 \\ 0 & S_y & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$TS = \begin{pmatrix} S_x & 0 & t_x \\ 0 & S_y & t_y \\ 0 & 0 & 1 \end{pmatrix}$$

$$RTS = \begin{pmatrix} S_x \cos\theta & -S_y \sin\theta & t_x \cos\theta - t_y \sin\theta \\ S_x \sin\theta & S_y \cos\theta & t_x \sin\theta + t_y \cos\theta \\ 0 & 0 & 1 \end{pmatrix}$$

$$P = \underbrace{RTS}_{P}$$

$$P^{-1} = S^{-1} T^{-1} R^{-1}$$

$$PP^{-1} = \underbrace{RTS}_{I} \underbrace{S^{-1} T^{-1} R^{-1}}_{I} = I$$

$$P^{-1}P = S^{-1} T^{-1} R^{-1} R T S = I_3$$

$$R_{\theta}^{-1} = R_{-\theta} = R_{\theta}^T = \begin{pmatrix} \cos\theta & \sin\theta & 0 \\ -\sin\theta & \cos\theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$T^{-1} \begin{pmatrix} t_x \\ t_y \\ 0 \end{pmatrix} = T \begin{pmatrix} -t_x \\ -t_y \\ 0 \end{pmatrix}$$

$$S^{-1} \begin{pmatrix} s_x \\ s_y \end{pmatrix} = S \begin{pmatrix} 1/s_x \\ 1/s_y \end{pmatrix}$$

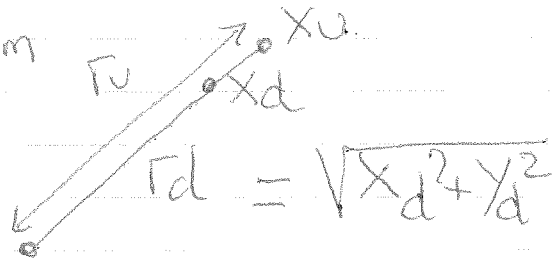
$$\textcircled{1} \quad X_d (1 + k_1 (X_d^2 + Y_d^2)) = X_0$$

$$\textcircled{2} \quad Y_d (1 + k_1 (X_d^2 + Y_d^2)) = Y_0$$

$$k_1 \text{ # mm}^{-2}$$

$$r_d = 500 \times 5.10 \text{ mm}^3$$

$$\begin{aligned} \delta &= r_0 - r_d \\ &= 0.01 \text{ mm} \end{aligned}$$



$$\textcircled{1} + \textcircled{2} \xrightarrow{2} (X_d^2 + Y_d^2) (1 + k_1 (X_d^2 + Y_d^2))^2 = X_0^2 + Y_0^2$$

$$r_d^2 (1 + k_1 r_d^2)^2 = r_0^2$$

$$(1 + k_1 r_d^2)^2 = \left(\frac{r_0}{r_d}\right)^2 = \left(1 + \frac{\delta}{r_d}\right)^2$$

$$k_1 = \frac{\delta}{r_d^3}$$

$$= \frac{0.01}{(2.5)^3} \text{ mm}^{-2}$$

$$= 6.4 \cdot 10^{-4} \text{ mm}^{-2}$$