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- Introductory lecture
- Segmenting binary images
- Feature extraction
- Image matching
- Stereo image matching
- 2D and 3D vision geometry (self taught)
- Camera calibration
- Stereo calibration
- 3D scene description /
- Understanding 27 February 2012

- Real-time image
 processing
- Rectification of stereo pairs
- Colour discrimination
- Features classification: PCA-LDA
- Higher level statistical approaches
- Course overview and final demo

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Slide 14

CD1 celine, 23/02/2009