

# Some Examples, Questions, and Answers: Lecture 2 – COMPSCI 369

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## Taylor Series

**Example 2.1:** Approximate the function  $f(x) = \log x$  (Fig. 1), i.e the natural logarithm of  $x$ , or the logarithm to the base  $e = 2.718281828\dots$ , in the neighbourhood of point  $x = 1.0$  using the Taylor polynomial of degree  $n = 6$ .

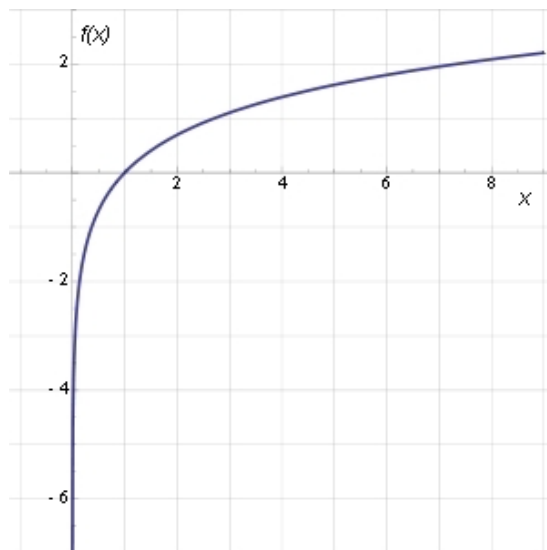


Figure 1: Function  $\log x$  ([http://en.wikipedia.org/wiki/Natural\\_logarithm](http://en.wikipedia.org/wiki/Natural_logarithm)).

**Solution:** First to sixth derivatives of the function  $f(x) = \log x$  for  $x > 0$ :

$$\begin{aligned}\frac{df(x)}{dx} &= \frac{1}{x}; & \frac{d^2f(x)}{dx^2} &= -\frac{1}{x^2}; & \frac{d^3f(x)}{dx^3} &= \frac{2!}{x^3}; \\ \frac{d^4f(x)}{dx^4} &= -\frac{3!}{x^4}; & \frac{d^5f(x)}{dx^5} &= \frac{4!}{x^5}; & \frac{d^6f(x)}{dx^6} &= -\frac{5!}{x^6}\end{aligned}$$

Therefore, the values of the function  $\log x$  and its derivatives at the point  $x = 1$  are, respectively,  $\log 1 = 0$  and

$$\begin{aligned} f^{(1)}(1) &\equiv \left. \frac{df(x)}{dx} \right|_{x=1} = 1; & f^{(2)}(1) &\equiv \left. \frac{d^2 f(x)}{dx^2} \right|_{x=1} = -1; \\ f^{(3)}(1) &\equiv \left. \frac{d^3 f(x)}{dx^3} \right|_{x=1} = 2! = 2; & f^{(4)}(1) &\equiv \left. \frac{d^4 f(x)}{dx^4} \right|_{x=1} = -3! = -6; \\ f^{(5)}(1) &\equiv \left. \frac{d^5 f(x)}{dx^5} \right|_{x=1} = 4! = 24; & f^{(6)}(1) &\equiv \left. \frac{d^6 f(x)}{dx^6} \right|_{x=1} = -5! = -120 \end{aligned}$$

Substituting these values into the Taylor polynomial (Lecture CS369-Roots-LinSys.pdf, Slide 3):

$$\begin{aligned} f(x) &= f(a) + (x-a)f^{(1)}(a) + \frac{1}{2!}(x-a)^2 f^{(2)}(a) + \frac{1}{3!}(x-a)^3 f^{(3)}(a) \\ &\quad + \frac{1}{4!}(x-a)^4 f^{(4)}(a) + \frac{1}{5!}(x-a)^5 f^{(5)}(a) + \frac{1}{6!}(x-a)^6 f^{(6)}(a) \end{aligned}$$

for  $a = 1$  gives the following polynomial approximation of the logarithmic function in the vicinity of  $x = 1$ :

$$\widehat{\log}_6(x; 1) = (x-1) - \frac{(x-1)^2}{2} + \frac{(x-1)^3}{3} - \frac{(x-1)^4}{4} + \frac{(x-1)^5}{5} - \frac{(x-1)^6}{6}$$

**Question 2.1** Approximate the same function  $f(x) = \log x$  in the neighbourhood of point  $x = a$  using the Taylor polynomial  $\widehat{\log}_6(x; a)$  of degree  $n = 6$ .

**Question 2.2** Approximate the exponential function  $f(x) = e^x$  in the neighbourhood of point  $x = a$  using the Taylor polynomial  $\widehat{e}_n(x; a)$  of degree  $n$ .

Hint: See Lecture CS369-Roots-LinSys.pdf, Slide 3.

## Newton's Root Finder

**Example 2.2** The Newton's iterative search for the root  $x^\circ$  of the cubic function  $f(x) = 2x^3 - 15x^2 + 36x - 23$  (i.e.  $f(x^\circ) = 0$ ) finds each next approximation  $x_{n+1}$  of the root by setting to zero the linear Taylor series expansion, i.e. by setting to zero the Taylor polynomial  $\widehat{f}_1(x; x_n) = f(x_n) + (x - x_n)f^{(1)}(x_n)$  of degree 1.

In other words, the Newton's method assumes that  $\widehat{f}_1(x_{n+1}; x_n) = 0$ , or – what is the same –  $f(x_n) + (x_{n+1} - x_n)f^{(1)}(x_n) = 0$ . This simple equation gives  $x_{n+1} = x_n - \frac{f(x_n)}{f^{(1)}(x_n)}$ . To implement this root finder, one needs the first derivative of the above cubic function:  $f^{(1)}(x) = 6x^2 - 30x + 36$ .

A simple C program implementing the Newton's search is given below:

```

/*****
 * Newton's method for a given cubic polynomial
 *****/
#include<stdlib.h>
#include<stdio.h>
#include<math.h>
double funct( double x );
double deriv( double x );
// Cubic polynomial
double funct( double x ) { return 2.*x*x*x-15.*x*x+ 36.*x-23.; }
// Derivative
double deriv( double x ) { return 6.*x*x-30.*x+36.; }

int main() {
    int    step = 0;           // iteration
    double drv,              // derivative value
           fnc,              // function value
           rc,               // current root value
           rn;              // new root value

    float  input;
    const double thresh = 1.e-4; // accuracy threshold
    const int  max_step = 100;   // max number of iterations

    printf("\nEnter initial root value: ");
    scanf("%f", &input );
    rn = (double)input;

    do {
        rc = rn;
        fnc = funct( rc );
        drv = deriv( rc );
        if ( fabs( drv ) < thresh ) {
            printf(
                "\nClose or equal to zero derivative at step %d\n",
                step );
            break;
        } else {
            rn = rc - fnc / drv; // Step towards the root
            printf(
                "\nStp%2i: old%7.5lf; fn%10.5lf  dr%10.5lf; new%7.5lf",
                step++, rc, fnc, drv, rn );
        }
    } while ( fabs( rn - rc ) >= thresh && step < max_step );
    printf("\n");
}

```

The above search converges to the goal value  $x^\circ = 1$  in five steps for the input  $x_0 = 0.0$  and in 14 steps for the input  $x_0 = 2.5$ :

---

Enter initial root value: 0.

Step	0:	root	0.00000;	fnc	-23.00000	drv	36.00000	new root	0.63889
Step	1:	root	0.63889;	fnc	-5.60112	drv	19.28241	new root	0.92937
Step	2:	root	0.92937;	fnc	-0.89320	drv	13.30132	new root	0.99652
Step	3:	root	0.99652;	fnc	-0.04189	drv	12.06274	new root	0.99999
Step	4:	root	0.99999;	fnc	-0.00011	drv	12.00016	new root	1.00000

---

Enter initial root value: 2.5

Step	0:	root	2.50000;	fnc	4.50000	drv	-1.50000	new root	5.50000
Step	1:	root	5.50000;	fnc	54.00000	drv	52.50000	new root	4.47143
Step	2:	root	4.47143;	fnc	16.86689	drv	21.81918	new root	3.69840
Step	3:	root	3.69840;	fnc	6.14458	drv	7.11695	new root	2.83503
Step	4:	root	2.83503;	fnc	4.07267	drv	-0.82655	new root	7.76235
Step	5:	root	7.76235;	fnc	288.05920	drv	164.65369	new root	6.01286
Step	6:	root	6.01286;	fnc	85.92943	drv	72.54113	new root	4.82830
Step	7:	root	4.82830;	fnc	26.25086	drv	31.02586	new root	3.98220
Step	8:	root	3.98220;	fnc	8.78927	drv	11.68155	new root	3.22980
Step	9:	root	3.22980;	fnc	4.18269	drv	1.69562	new root	0.76303
Step	10:	root	0.76303;	fnc	-3.37561	drv	16.60235	new root	0.96635
Step	11:	root	0.96635;	fnc	-0.41402	drv	12.61243	new root	0.99918
Step	12:	root	0.99918;	fnc	-0.00985	drv	12.01476	new root	1.00000
Step	13:	root	1.00000;	fnc	-0.00001	drv	12.00001	new root	1.00000

---

Notice that convergence of the Newton's search is not necessarily monotone depending on closeness of linear approximation at each successive guess  $x_n$ , i.e.  $\hat{f}_1(x; x_n) = f(x_n) + (x - x_n)f^{(1)}(x_n)$ , starting from the initial guess  $x_0$ , to the function  $f(x)$  between  $x_n$  and the true root  $x^\circ$ . Moreover, in some cases the process may even diverge from the goal root.

**Question 2.3:** What result of the above search will be obtained for the input guess  $x_0 = 2.0$  and why? Can you predict the search result for the input  $x_0 = 3.0$ ?

**Question 2.4:** Find results of the above search for the input guesses  $x_0 = -1, -0.5, 0.5, 1.5, 2.1, 3.1, 3.9, 4.0, 5.0$ . Does the number of steps to convergence relate only to the closeness between the initial guess and the true root  $x^\circ = 1.0$  or it depends also on the closeness between the function and its linear approximation?

**Question 2.5:** Implement the Newton's search and find the root of the function  $f(x) = \log x - \frac{1}{x}$ ;  $x > 0$ , starting from the initial guesses  $x_0 = 1.0$  and  $x_0 = 2.0$ .

*Hint:* the first derivative is positive,  $f^{(1)}(x) = \frac{1}{x} + \frac{1}{x^2} > 0$ , for all  $x > 0$ .

## Systems of Linear Equations: Gaussian Elimination

**Example 2.3:** Transforming the system

$$\begin{cases} 6x + 2y - 3z = 1 \\ 12x - y + 4z = 22 \\ 18x + 5y - 5z = 13 \end{cases}, \text{ or } \overbrace{\begin{bmatrix} 6 & 2 & -3 \\ 12 & -1 & 4 \\ 18 & 5 & -5 \end{bmatrix}}^{\mathbf{A}} \overbrace{\begin{bmatrix} x \\ y \\ z \end{bmatrix}}^{\mathbf{x}} = \overbrace{\begin{bmatrix} 1 \\ 22 \\ 13 \end{bmatrix}}^{\mathbf{b}}$$

into upper triangular form by sequential elimination of lower parts of the columns.

**Eliminating the first column:** Deducting the scaled first row from each lower row with the scale factors, being the ratio between the corresponding first coefficients (in order to eliminate the first column elements):

$$\begin{aligned} \text{Row 1 : } & 6x + 2y - 3z = 1 \\ \text{Row 2 : } & 12x - y + 4z - \frac{12}{6}(6x + 2y - 3z) = 22 - \frac{12}{6} \cdot 1 \Rightarrow -5y + 10z = 20 \\ \text{Row 3 : } & 18x + 5y - 5z - \frac{18}{6}(6x + 2y - 3z) = 13 - \frac{18}{6} \cdot 1 \Rightarrow -y + 4z = 10 \end{aligned}$$

– eliminates all the elements of the first column below the main diagonal:

$$\begin{cases} 6x + 2y - 3z = 1 \\ -5y + 10z = 20 \\ -y + 4z = 10 \end{cases}, \text{ or } \begin{bmatrix} 6 & 2 & -3 \\ 0 & -5 & 10 \\ 0 & -1 & 4 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ 20 \\ 10 \end{bmatrix}$$

In the matrix form such elimination is represented by left-multiplying the initial matrix  $\mathbf{A}$  and vector  $\mathbf{b}$  with the eliminating matrix  $\mathbf{M}_1$ , which has the unit main diagonal and the negated scaling factors along the first column,  $\mathbf{M}_1\mathbf{A}\mathbf{x} = \mathbf{M}_1\mathbf{b}$ :

$$\underbrace{\begin{bmatrix} 1 & 0 & 0 \\ -\frac{12}{6} = -2 & 1 & 0 \\ -\frac{18}{6} = -3 & 0 & 1 \end{bmatrix}}_{\mathbf{M}_1} \underbrace{\begin{bmatrix} 6 & 2 & -3 \\ 12 & -1 & 4 \\ 18 & 5 & -5 \end{bmatrix}}_{\mathbf{A}} \mathbf{x} = \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ -\frac{12}{6} = -2 & 1 & 0 \\ -\frac{18}{6} = -3 & 0 & 1 \end{bmatrix}}_{\mathbf{M}_1} \underbrace{\begin{bmatrix} 1 \\ 22 \\ 13 \end{bmatrix}}_{\mathbf{b}}$$

$$\mathbf{M}_1\mathbf{A} = \begin{bmatrix} 6 & 2 & -3 \\ 0 & -5 & 10 \\ 0 & -1 & 4 \end{bmatrix} \qquad \mathbf{M}_1\mathbf{b} = \begin{bmatrix} 1 \\ 20 \\ 10 \end{bmatrix}$$

**Eliminating the second column:** The like deduction of the scaled second row of the system  $\mathbf{M}_1\mathbf{A}\mathbf{x} = \mathbf{M}_1\mathbf{b}$  from the lower one finalises the transformation in this particular example:

$$\begin{aligned} \text{Row 1 : } & 6x + 2y - 3z = 1 \\ \text{Row 2 : } & -5y + 10z = 20 \\ \text{Row 3 : } & -y + 4z - \frac{-1}{-5}(-5y + 10z) = 10 - \frac{-1}{-5} \cdot 20 \Rightarrow 2z = 6 \end{aligned}$$

by eliminating all the elements of the second column below the main diagonal:

$$\begin{cases} 6x + 2y - 3z = 1 \\ -5y + 10z = 20 \\ 2z = 6 \end{cases}, \text{ or } \begin{bmatrix} 6 & 2 & -3 \\ 0 & -5 & 10 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ 20 \\ 6 \end{bmatrix}$$

In the matrix form such elimination is represented by left-multiplying the matrix  $\mathbf{M}_1\mathbf{A}$  and vector  $\mathbf{M}_1\mathbf{b}$  with the eliminating matrix  $\mathbf{M}_2$ , which has the unit main diagonal and the negated scaling factors below the main diagonal along the second column,  $\mathbf{M}_2\mathbf{M}_1\mathbf{A} = \mathbf{M}_2\mathbf{M}_1\mathbf{b}$ :

$$\underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -\frac{-1}{-5} & 1 \end{bmatrix}}_{\mathbf{M}_2} \underbrace{\begin{bmatrix} 6 & 2 & -3 \\ 0 & -5 & 10 \\ 0 & -1 & 4 \end{bmatrix}}_{\mathbf{M}_1\mathbf{A}} \mathbf{x} = \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -\frac{-1}{-5} & 1 \end{bmatrix}}_{\mathbf{M}_2} \underbrace{\begin{bmatrix} 1 \\ 20 \\ 10 \end{bmatrix}}_{\mathbf{M}_1\mathbf{b}}$$

$$\underbrace{\mathbf{M}_2\mathbf{M}_1\mathbf{A}}_{\mathbf{c}} = \begin{bmatrix} 6 & 2 & -3 \\ 0 & -5 & 10 \\ 0 & 0 & 2 \end{bmatrix} \quad \underbrace{\mathbf{M}_2\mathbf{M}_1\mathbf{b}}_{\mathbf{c}} = \begin{bmatrix} 1 \\ 20 \\ 6 \end{bmatrix}$$

**Solving the system:** The resulting upper triangular system  $\mathbf{C}\mathbf{x} = \mathbf{c}$  is solved by back-substitution:

$$\left. \begin{aligned} 2z = 6z &\Rightarrow z = \frac{6}{2} = 3 \\ -5y + 10z = 20 &\Rightarrow y = \frac{1}{-5}(20 - 10 \cdot 3) = 2 \\ 6x + 2y - 3z = 1 &\Rightarrow x = \frac{1}{6}(1 - 2 \cdot 2 + 3 \cdot 3) = 1 \end{aligned} \right\}, \text{ that is, } \mathbf{x} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$$

**Question 2.6:** How does Gaussian elimination relate to LU decomposition that represents a square matrix  $\mathbf{A}$  as the product of a lower triangular matrix,  $\mathbf{L}$ , and an upper triangular matrix,  $\mathbf{U}$ , i.e.  $\mathbf{A} = \mathbf{LU}$ ?

*Hint:* See [http://en.wikipedia.org/wiki/LU\\_decomposition](http://en.wikipedia.org/wiki/LU_decomposition).

**Question 2.7:** Solve by hand the system  $\underbrace{\begin{bmatrix} 1 & 4 \\ 2 & 6 \end{bmatrix}}_{\mathbf{A}} \underbrace{\begin{bmatrix} x \\ y \end{bmatrix}}_{\mathbf{x}} = \underbrace{\begin{bmatrix} 3 \\ 4 \end{bmatrix}}_{\mathbf{b}}$  of two linear equations using Gaussian elimination and perform LU decomposition of its matrix  $\mathbf{A}$ .

## Answers

**To Question 2.1:** At an arbitrary point  $x = a$  the function value is  $\log a$  and the values of the derivatives are  $f^{(k)} = (-1)^{k-1} \frac{(k-1)!}{a^k}$ . Therefore,

$$\log x = \log a + \frac{x-a}{a} - \frac{(x-a)^2}{2a^2} + \frac{(x-a)^3}{3a^3} - \frac{(x-a)^4}{4a^4} + \frac{(x-a)^5}{5a^5} - \frac{(x-a)^6}{6a^6}$$

**To Question 2.2:** At an arbitrary point  $x = a$  both the function and all the derivatives have the same value  $e^a$ . Therefore, the Taylor polynomial of degree  $n$  is as follows:

$$\hat{e}_n(x; a) = e^a \left( 1 + \frac{x-a}{1!} + \frac{(x-a)^2}{2!} + \frac{(x-a)^3}{3!} + \dots + \frac{(x-a)^n}{n!} \right)$$

**To Question 2.3:** The search fails for the initial guess  $x_0 = 2.0$  because at this point the first derivative is equal to zero:  $f^{(1)}(2.0) = 0.0$ :

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Enter initial root value: 2

Close or equal to zero derivative at step 0

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In this example the first derivative is a quadratic polynomial,  $6x^2 - 30x + 36$ , with two own roots,  $x = 2.0$  and  $x = 3.0$ , which correspond to the local maximum and the local minimum of the cubic polynomial  $f(x)$  under consideration. Therefore, the like search failure is expected for the input  $x_0 = 3.0$ .

**To Question 2.4:** The search results below illustrate that the closer the linear approximations at the initial point  $x_0$  and all the subsequent points  $x_n$ ;  $n = 1, 2, \dots$  to the function  $f(x)$  itself within neighbourhood of the true root  $x^\circ$ ;  $f(x^\circ) = 0$ , the faster the convergence. If the linear approximations deviate much from the function itself, then the convergence may become non-monotonous or the process may even divergence from the goal root.

---

Enter initial root value: -1.

Step 0:	root	-1.00000	fnc	-76.00000	drv	72.00000	new root	0.05556
Step 1:	root	0.05556	fnc	-21.04595	drv	34.35185	new root	0.66821
Step 2:	root	0.66821	fnc	-5.04522	drv	18.63264	new root	0.93899
Step 3:	root	0.93899	fnc	-0.76611	drv	13.12057	new root	0.99738
Step 4:	root	0.99738	fnc	-0.03153	drv	12.04725	new root	0.99999
Step 5:	root	0.99999	fnc	-0.00006	drv	12.00009	new root	1.00000

Enter initial root value: -0.5

Step 0:	root	-0.50000	fnc	-45.00000	drv	52.50000	new root	0.35714
Step 1:	root	0.35714	fnc	-11.96501	drv	26.05102	new root	0.81643
Step 2:	root	0.81643	fnc	-2.51842	drv	15.50636	new root	0.97885
Step 3:	root	0.97885	fnc	-0.25788	drv	12.38344	new root	0.99967
Step 4:	root	0.99967	fnc	-0.00394	drv	12.00591	new root	1.00000
Step 5:	root	1.00000	fnc	-0.00000	drv	12.00000	new root	1.00000

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Enter initial root value: 0.5

Step 0:	root 0.50000;	fnc -8.50000	drv 22.50000	new root 0.87778
Step 1:	root 0.87778;	fnc -1.60476	drv 14.28963	new root 0.99008
Step 2:	root 0.99008;	fnc -0.11992	drv 12.17914	new root 0.99993
Step 3:	root 0.99993;	fnc -0.00088	drv 12.00131	new root 1.00000

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Enter initial root value: 1.5

Step 0:	root 1.50000;	fnc 4.00000	drv 4.50000	new root 0.61111
Step 1:	root 0.61111;	fnc -6.14540	drv 19.90741	new root 0.91981
Step 2:	root 0.91981;	fnc -1.02118	drv 13.48199	new root 0.99555
Step 3:	root 0.99555;	fnc -0.05353	drv 12.08014	new root 0.99999
Step 4:	root 0.99999;	fnc -0.00018	drv 12.00027	new root 1.00000

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Enter initial root value: 2.1

Step 0:	root 2.10000;	fnc 4.97200	drv -0.54000	new root 11.30742
Step 1:	root 11.30742;	fnc 1357.68119	drv 463.92338	new root 8.38089
Step 2:	root 8.38089;	fnc 402.45927	drv 206.00955	new root 6.42730
Step 3:	root 6.42730;	fnc 119.75590	drv 91.04210	new root 5.11191
Step 4:	root 5.11191;	fnc 36.21939	drv 39.43242	new root 4.19339
Step 5:	root 4.19339;	fnc 11.67176	drv 15.70544	new root 3.45022
Step 6:	root 3.45022;	fnc 4.79063	drv 3.91756	new root 2.22736
Step 7:	root 2.22736;	fnc 4.86842	drv -1.05402	new root 6.84629
Step 8:	root 6.84629;	fnc 162.18502	drv 111.84122	new root 5.39615
Step 9:	root 5.39615;	fnc 48.73975	drv 48.82610	new root 4.39792
Step 10:	root 4.39792;	fnc 15.32608	drv 20.11256	new root 3.63590
Step 11:	root 3.63590;	fnc 5.72740	drv 6.24165	new root 2.71829
Step 12:	root 2.71829;	fnc 4.19336	drv -1.21409	new root 6.17221
Step 13:	root 6.17221;	fnc 98.03232	drv 79.41087	new root 4.93772
Step 14:	root 4.93772;	fnc 29.81554	drv 34.15480	new root 4.06476
Step 15:	root 4.06476;	fnc 9.81547	drv 13.19093	new root 3.32066
Step 16:	root 3.32066;	fnc 4.37440	drv 2.54087	new root 1.59904
Step 17:	root 1.59904;	fnc 4.38877	drv 3.37037	new root 0.29688
Step 18:	root 0.29688;	fnc -13.58214	drv 27.62251	new root 0.78858
Step 19:	root 0.78858;	fnc -2.95819	drv 16.07370	new root 0.97262
Step 20:	root 0.97262;	fnc -0.33533	drv 12.49731	new root 0.99945
Step 21:	root 0.99945;	fnc -0.00656	drv 12.00984	new root 1.00000
Step 22:	root 1.00000;	fnc -0.00000	drv 12.00000	new root 1.00000

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Enter initial root value: 3.1

Step 0:	root 3.10000;	fnc 4.03200	drv 0.66000	new root -3.00910
Step 1:	root -3.00910;	fnc -321.64024	drv 180.60092	new root -1.22815
Step 2:	root -1.22815;	fnc -93.54386	drv 81.89473	new root -0.08591
Step 3:	root -0.08591;	fnc -26.20463	drv 38.62150	new root 0.59259
Step 4:	root 0.59259;	fnc -6.51799	drv 20.32925	new root 0.91321
Step 5:	root 0.91321;	fnc -1.11055	drv 13.60737	new root 0.99483
Step 6:	root 0.99483;	fnc -0.06233	drv 12.09329	new root 0.99998
Step 7:	root 0.99998;	fnc -0.00024	drv 12.00036	new root 1.00000

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Enter initial root value: 3.9

Step 0:	root 3.90000;	fnc 7.88800	drv 10.26000	new root 3.13119
Step 1:	root 3.13119;	fnc 4.05615	drv 0.89040	new root -1.42424
Step 2:	root -1.42424;	fnc -110.47741	drv 90.89788	new root -0.20884
Step 3:	root -0.20884;	fnc -31.19054	drv 42.52679	new root 0.52460
Step 4:	root 0.52460;	fnc -7.95382	drv 21.91333	new root 0.88756
Step 5:	root 0.88756;	fnc -1.46586	drv 14.09971	new root 0.99153
Step 6:	root 0.99153;	fnc -0.10232	drv 12.15294	new root 0.99995
Step 7:	root 0.99995;	fnc -0.00064	drv 12.00096	new root 1.00000

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Enter initial root value: 4

Step 0:	root 4.00000;	fnc 9.00000	drv 12.00000	new root 3.25000
Step 1:	root 3.25000;	fnc 4.21875	drv 1.87500	new root 1.00000
Step 2:	root 1.00000;	fnc 0.00000	drv 12.00000	new root 1.00000

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Enter initial root value: 5

Step 0:	root 5.00000;	fnc 32.00000	drv 36.00000	new root 4.11111
Step 1:	root 4.11111;	fnc 10.44719	drv 14.07407	new root 3.36881
Step 2:	root 3.36881;	fnc 4.50840	drv 3.02899	new root 1.88040
Step 3:	root 1.88040;	fnc 4.95366	drv 0.80345	new root -4.28513
Step 4:	root -4.28513;	fnc -610.06866	drv 274.72760	new root -2.06449
Step 5:	root -2.06449;	fnc -178.85222	drv 123.50767	new root -0.61639
Step 6:	root -0.61639;	fnc -51.35739	drv 56.77127	new root 0.28825
Step 7:	root 0.28825;	fnc -13.82147	drv 27.85107	new root 0.78451
Step 8:	root 0.78451;	fnc -3.02379	drv 16.15740	new root 0.97166
Step 9:	root 0.97166;	fnc -0.34739	drv 12.51499	new root 0.99942
Step 10:	root 0.99942;	fnc -0.00702	drv 12.01053	new root 1.00000
Step 11:	root 1.00000;	fnc -0.00000	drv 12.00000	new root 1.00000

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**To Question 2.5:** This function is smooth with no local extrema (its first derivative is positive for  $x > 0$ ). Thus the search converges monotonously in 4 – 5 steps to the goal root:

Enter initial root value: 1.

Step 0:	root 1.00000;	fnc -1.00000	drv 2.00000	new root 1.50000
Step 1:	root 1.50000;	fnc -0.26120	drv 1.11111	new root 1.73508
Step 2:	root 1.73508;	fnc -0.02529	drv 0.90851	new root 1.76292
Step 3:	root 1.76292;	fnc -0.00027	drv 0.88901	new root 1.76322
Step 4:	root 1.76322;	fnc -0.00000	drv 0.88879	new root 1.76322

Enter initial root value: 2.

Step 0:	root 2.00000;	fnc 0.19315	drv 0.75000	new root 1.74247
Step 1:	root 1.74247;	fnc -0.01859	drv 0.90326	new root 1.76306
Step 2:	root 1.76306;	fnc -0.00015	drv 0.88891	new root 1.76322
Step 3:	root 1.76322;	fnc -0.00000	drv 0.88879	new root 1.76322

**To Question 2.6:** LU decomposition is the matrix form of Gaussian elimination, which converts a non-singular linear system,  $\mathbf{Ax} = \mathbf{b}$ , of  $m$  equations with  $m$  unknowns into the equivalent linear system  $\mathbf{Cx} = \mathbf{c}$  with the upper triangular  $m \times m$  matrix  $\mathbf{C} = \mathbf{M}_{m-1} \cdots \mathbf{M}_2 \mathbf{M}_1 \mathbf{A}$ . Because all the eliminating matrices  $\mathbf{M}_i$ ;  $i = 1, \dots, m - 1$ , are non-singular (invertible), the elimination implicitly builds the LU decomposition:

$$\mathbf{A} = \underbrace{\mathbf{M}_1^{-1} \mathbf{M}_2^{-1} \cdots \mathbf{M}_{m-1}^{-1}}_{\mathbf{L}} \underbrace{\mathbf{C}}_{\mathbf{U}}$$

In our Example 2.3,

$$\underbrace{\begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ -3 & 0 & 1 \end{bmatrix}^{-1}}_{\mathbf{M}_1^{-1}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -0.2 & 1 \end{bmatrix}^{-1}}_{\mathbf{M}_2^{-1}} = \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 0 & 1 \end{bmatrix}}_{\mathbf{M}_1^{-1}} \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0.2 & 1 \end{bmatrix}}_{\mathbf{M}_2^{-1}} = \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 0.2 & 1 \end{bmatrix}}_{\mathbf{L}}$$

and the initial matrix  $\mathbf{A}$  has the following LU decomposition:

$$\underbrace{\begin{bmatrix} 6 & 2 & -3 \\ 12 & -1 & 4 \\ 18 & 5 & -5 \end{bmatrix}}_{\mathbf{A}} = \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 0.2 & 1 \end{bmatrix}}_{\mathbf{L}} \underbrace{\begin{bmatrix} 6 & 2 & -3 \\ 0 & -5 & 10 \\ 0 & 0 & 2 \end{bmatrix}}_{\mathbf{U}(\equiv \mathbf{C})}$$

**To Question 2.7:**  $\begin{bmatrix} 1 & 4 \\ 2 & 6 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 3 \\ 4 \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & 4 \\ 0 & -2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 3 \\ -2 \end{bmatrix} \Rightarrow$   
 $y = \frac{-2}{-2} = 1$   
 $x = \frac{3-4 \cdot 1}{1} = -1$   
 $\Leftrightarrow \underbrace{\begin{bmatrix} 1 & 4 \\ 2 & 6 \end{bmatrix}}_{\mathbf{A}} = \underbrace{\begin{bmatrix} 1 & 0 \\ 2 & 1 \end{bmatrix}}_{\mathbf{L}} \underbrace{\begin{bmatrix} 1 & 4 \\ 0 & -2 \end{bmatrix}}_{\mathbf{U}}$