

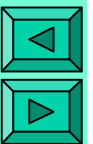


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# CBIR: Colour Representation

COMPSCI.708.S1.C

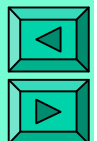
A/P Georgy Gimel'farb





# Colour Representation

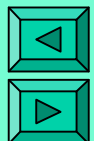
- **Colour** is the most widely used visual feature in multimedia context
- CBIR systems are not aware of the difference in *original*, *encoded*, and *perceived* colours
- Colour is a subjective characteristic
  - It tells how the perceived electromagnetic radiation,  $F(\lambda)$ , is distributed in the range  $[380 \text{ nm}, 780 \text{ nm}]$  of wavelengths  $\lambda$  of visible light





# Chrominance

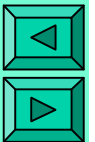
- Composition of wavelengths gives **chrominance**
  - It is specified by **hue** (the dominant wavelengths) and **saturation** (the purity) of a colour
  - A pure colour has 100% of saturation
  - All shades of colourless (grey) light, e.g. white light, have 0% of saturation
- To design colour descriptors, one should specify colour space, its partitioning, and how to measure similarity between colours





# RGB Primary Colours

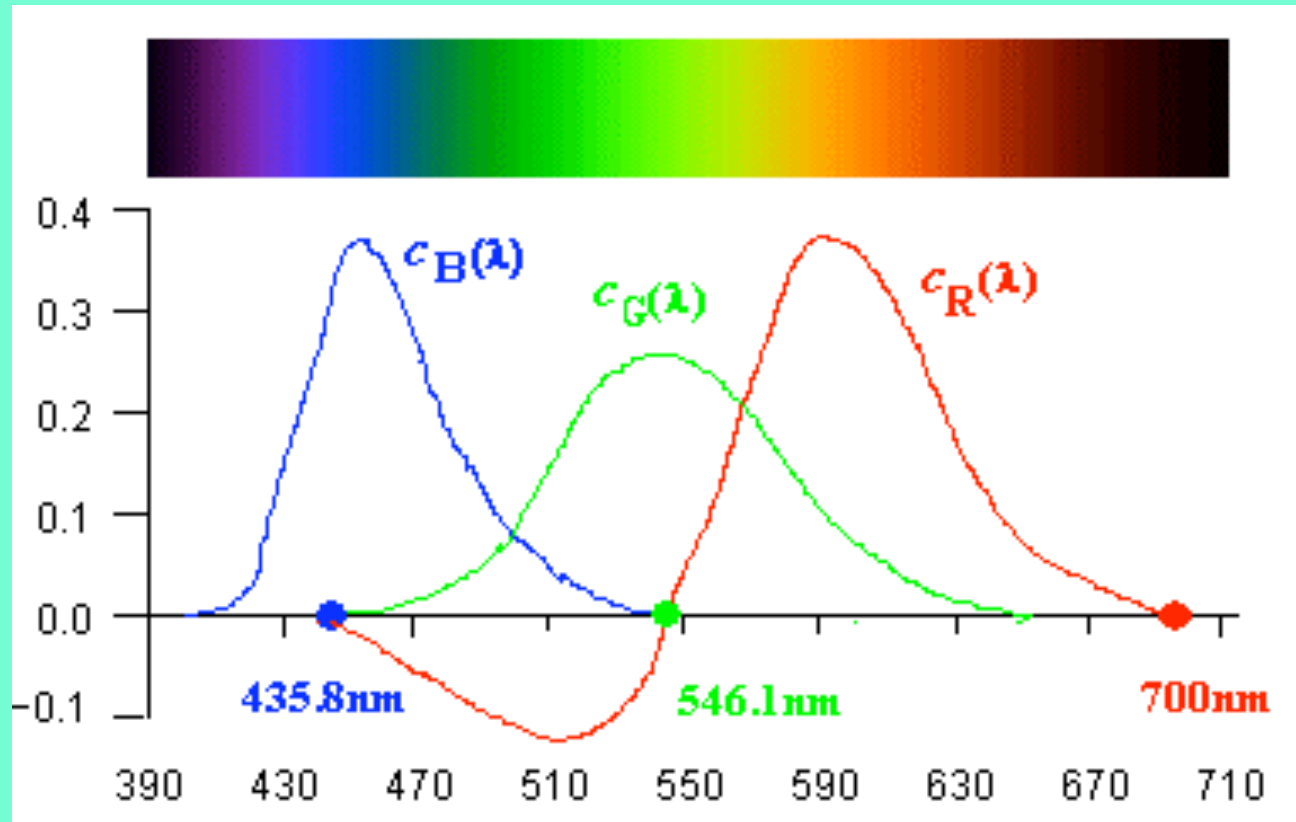
- A ***colour space*** is a multidimensional space of colour components (typically, the 3D colour space)
- Human vision combines three primary colours: **Red (R,  $\lambda = 700 \text{ nm}$ )**, **Green (G,  $\lambda = 546.1 \text{ nm}$ )**, and **Blue (B,  $\lambda = 435.8 \text{ nm}$ )**
- Any visible colour is a linear combination of the three primary colours (**R, G, B**) with the particular weights  $c_R(\lambda)$ ,  $c_G(\lambda)$ ,  $c_B(\lambda)$



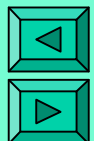


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# RGB Combinations of Colours



$$F(\lambda) = R c_R(\lambda) + G c_G(\lambda) + B c_B(\lambda)$$



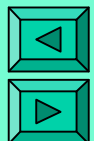


# XYZ Primary Colours

- The unreal primary colours **XYZ** pursue the goal of obtaining only non-negative weights  $c_X(\lambda)$ ,  $c_Y(\lambda)$ ,  $c_Z(\lambda)$  in the colour representation:

$$F(\lambda) = X c_X(\lambda) + Y c_Y(\lambda) + Z c_Z(\lambda)$$

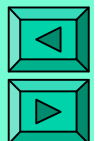
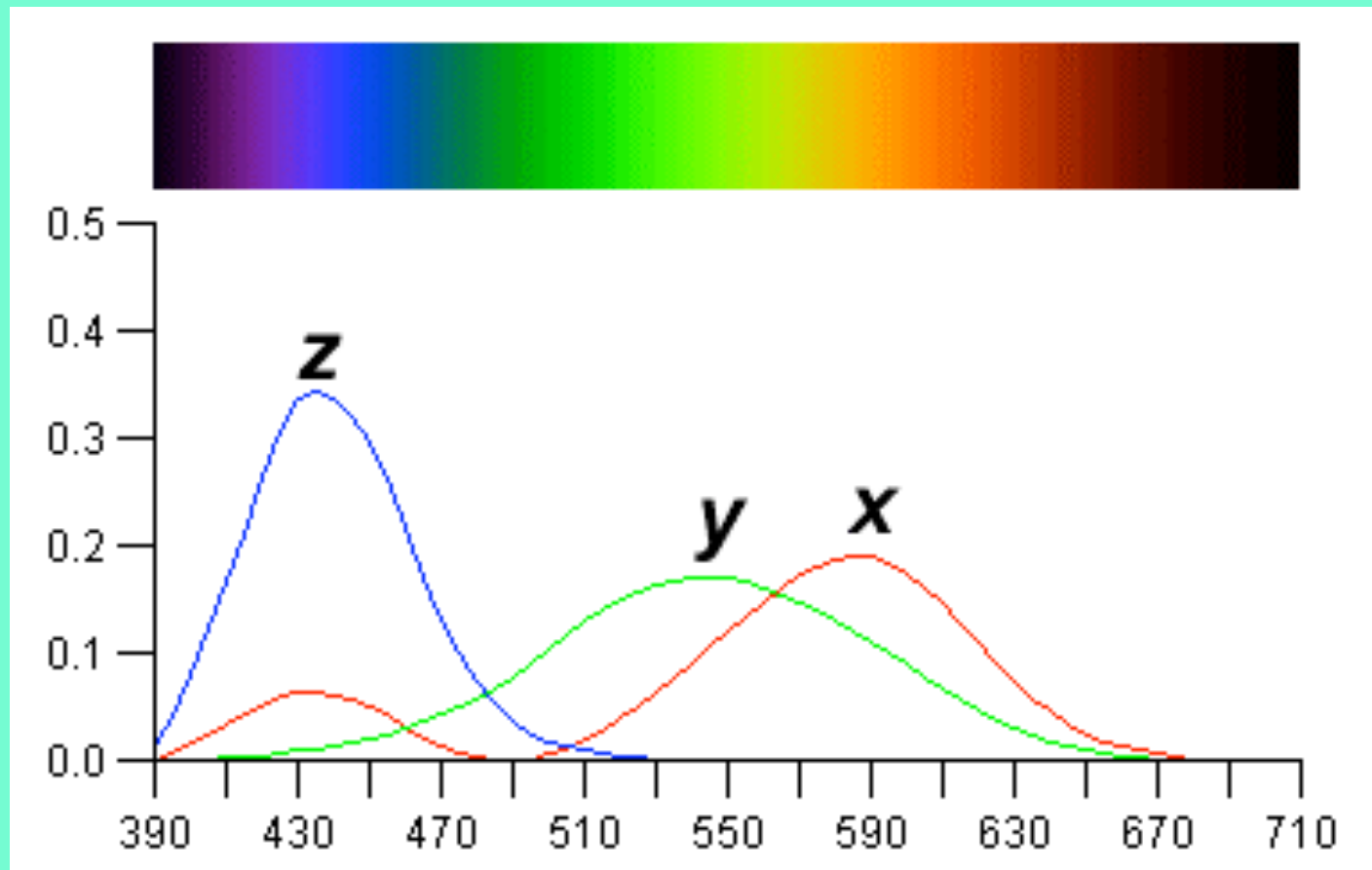
- The **XYZ** chromaticity diagrams are defined by the **Commission Internationale de l'Eclairage (CIE)** for 1931 2° Standard Observer and 1964 10° Standard Observer





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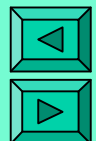
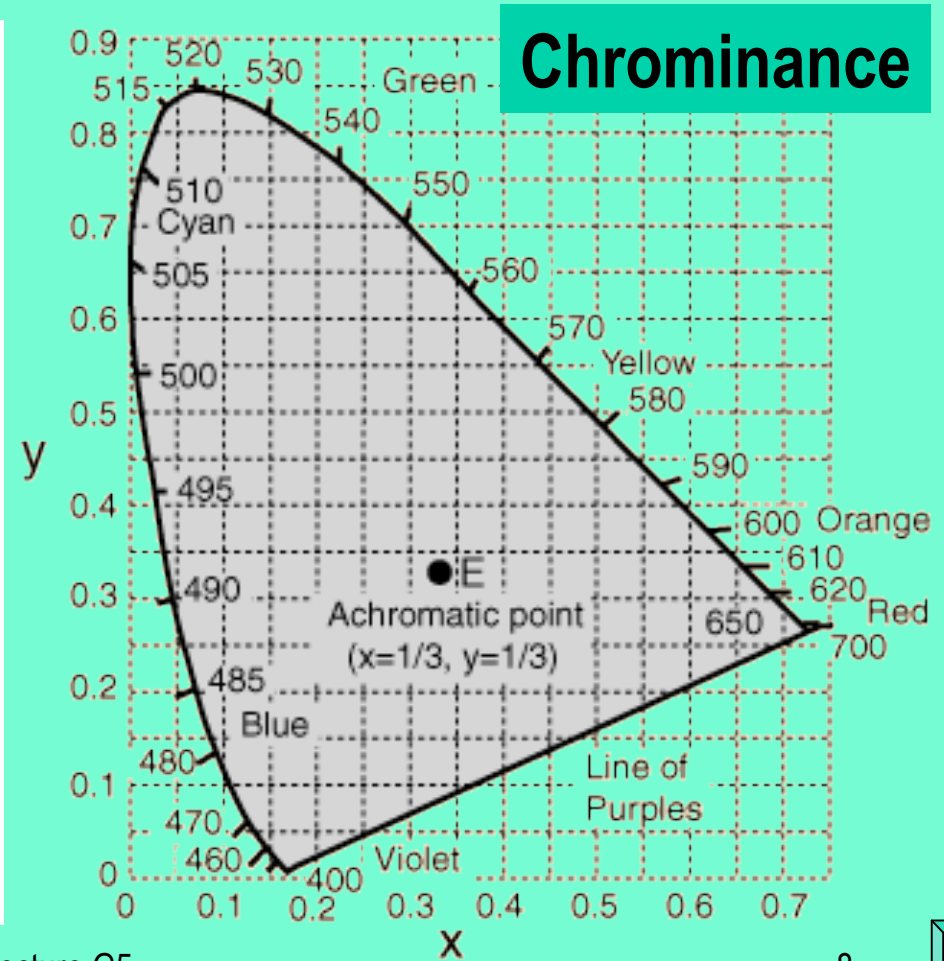
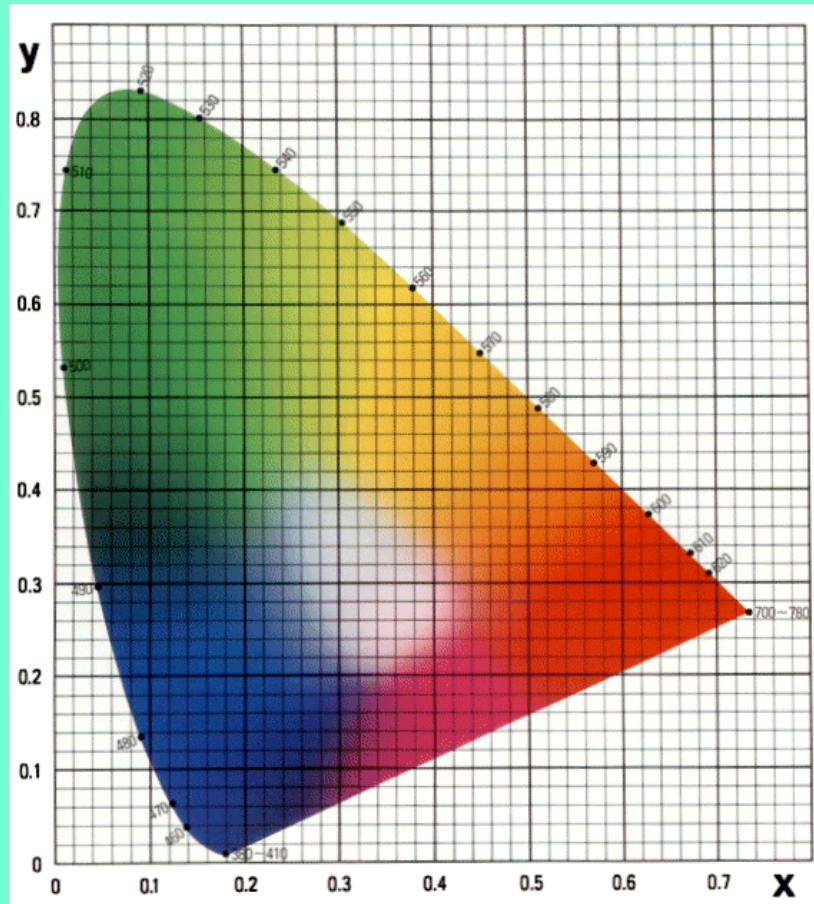
# XYZ Combinations of Colours





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# CIE 1931 XYZ Colour Diagram

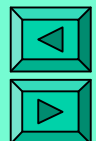
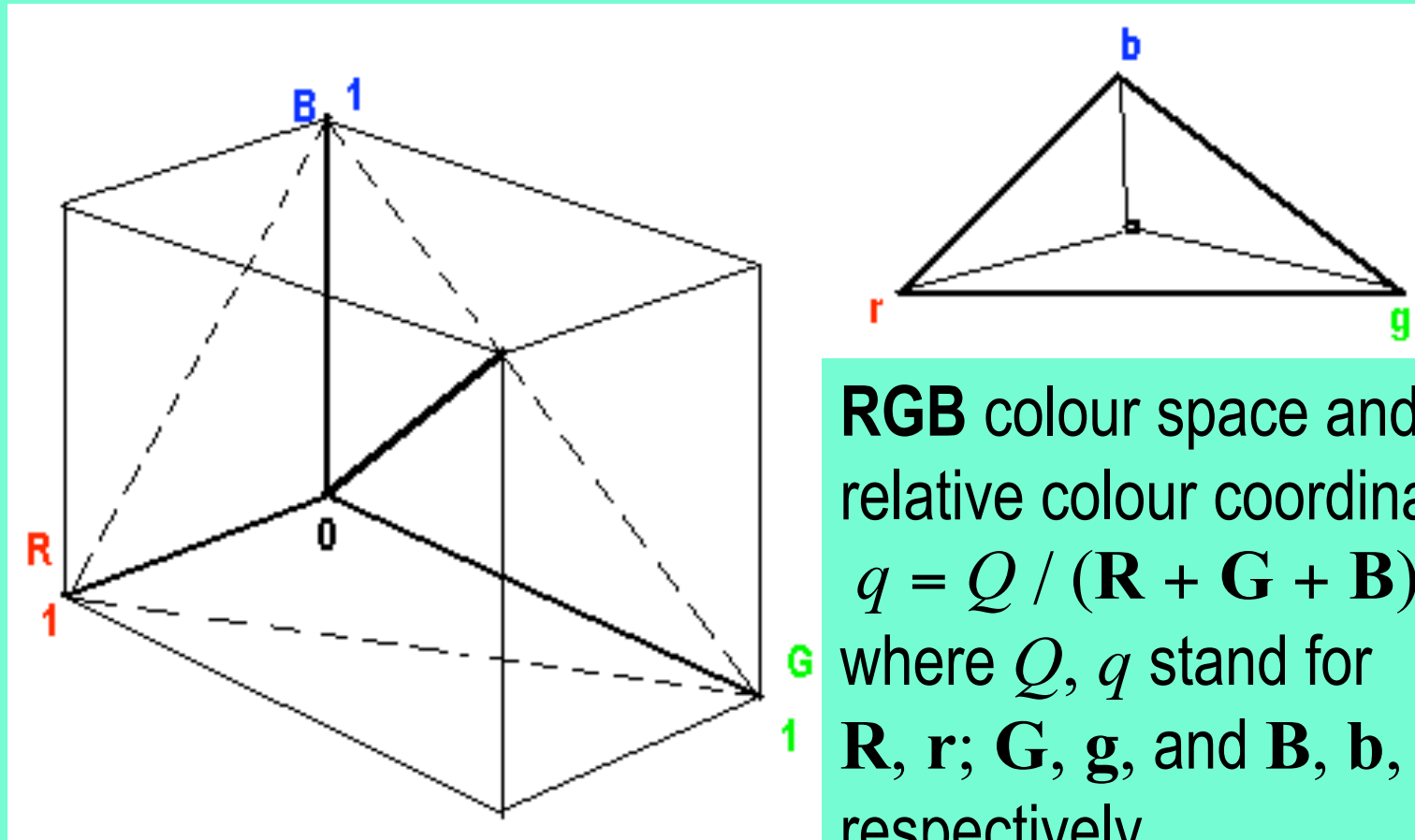






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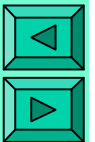
# RGB Colour Space





# RGB Colour Space

- The **RGB** representation is most popular:
  - It closely relates to human colour perception
  - A majority of imaging devices produce RGB images
- **Gamma correction** of a non-linear relationship  $S = L^\gamma$  between the signal  $S$  and light intensity  $L$  in imaging devices before storing, transmitting, or processing the images





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# RGB Image Components



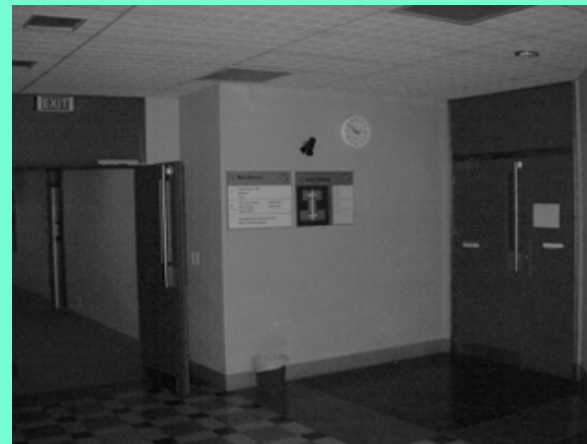
RGB



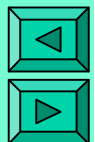
R



G



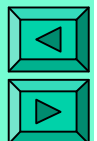
B





# A Variety of RGB Spaces

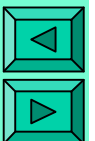
- **RGB** spaces in different application domains:
  - Linear w.r.t. **XYZ**, not CIE-based (scanners, cameras)
  - Non-linear CIE-based **RGB** spaces (displays, TV)
  - Colorimetric **sRGB** standard (the Internet)
- The **RGB** space is not perceptually uniform: distances do not reflect perceptual dissimilarity
- A large number of spaces derived from the **RGB** have been used in practice for query-by-colour applications





# RGB and Query-by-Colour

- The initial **RGB** representation of an image is of retrieval value only if recording was performed in stable conditions
  - Only in rare cases, e.g. for art paintings
- **RGB** coordinates are strongly interdependent
  - **RGB** coordinates describe not only inherent colour properties of objects but also variations of illumination and other external factors





# Independent Chrominance

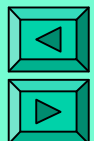
- Luminance (e.g.,  $R+B+G$ ) is separated from the two **orthogonal chrominance** components that form independent (or opponent) axes:

$$R + G + B, R - G, -R - G + 2B$$

- Luminance and relative 2D colour coordinates:

$$R \ G \ B \Rightarrow r \ g \ b \ (r + g + b = 1);$$

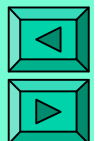
$$r = R / (R+B+G); g = G / (R+B+G); b = B / (R+B+G)$$





# Independent Chrominance

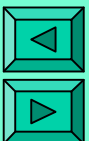
- Luminance can be down-sampled
  - human vision is more sensitive to chrominance than to brightness
- Chrominance components: invariant to changes in illumination intensity and shadows
  - RGB-to-”Luminance-Chrominance” transformations are computationally simple
  - But: the resulting colour spaces are neither uniform, nor natural





# HSI (HSV) Colour Space

- **HSI** (*hue–saturation–intensity*) or **HSV** (*hue–saturation–value*) is a non-linearly transformed **RGB** space:
  - The brightness (value, intensity)  $I = (R + G + B) / 3$  axis is orthogonal to the chrominance plane
  - The saturation **S** and the hue **H** are the radius and angle, respectively, of the polar coordinates in the chrominance plane
  - This space is approximately **perceptually uniform**

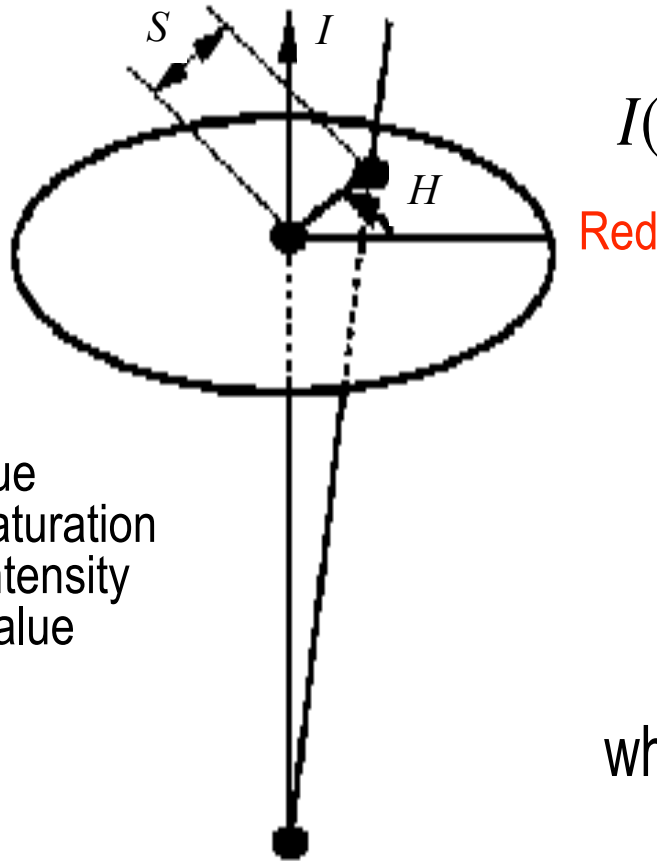






# HSI (HSV) Colour Space

## Conversion from RGB to HSI



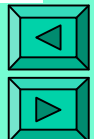
*H* - hue  
*S* - saturation  
*I* - intensity  
*V* - value

$$I(\text{or } V) = \frac{1}{3}(R + G + B)$$

$$S = 1 - \frac{\min\{R, G, B\}}{I}$$

$$H = \begin{cases} \delta & \text{if } B < G \\ 360^\circ - \delta & \text{otherwise} \end{cases}$$

$$\text{where } \delta = \cos^{-1} \left( \frac{0.5((R - G) + (R - B))}{\sqrt{(R - G)^2 + (R - B)(G - B)}} \right)$$





# HSI/HSV in MPEG-7

$$I \text{ (or } V) = \max\{R, G, B\}$$

$$S = 1 - \frac{\min\{R, G, B\}}{I}$$

$$H = \begin{cases} 60(G-B)/(R-B) & \text{if } R > G > B \\ 360 - 60(B-G)/(R-G) & \text{if } R > B > G \\ 120 - 60(R-B)/(G-B) & \text{if } G > R > B \\ 120 + 60(B-R)/(G-R) & \text{if } G > B > R \\ 240 + 60(R-G)/(B-G) & \text{if } B > R > G \\ 240 - 60(G-R)/(B-R) & \text{if } B > G > R \\ \text{undefined (achromatic colour)} & \text{if } R = G = B \end{cases}$$

In MPEG-7 the HSI / HSV colour space is defined in a different way involving both the maximum and the minimum RGB components

