



THE UNIVERSITY OF AUCKLAND
NEW ZEALAND

COMPSCI 366 S1 C 2005
Foundations of Artificial Intelligence

Hans W. Guesgen
Computer Science Department

Assignment 2: A* Search in a Maze

Worth: 4% [40 marks]

Due Date: Friday, 15 April 2005

Submission: Assignment Drop Box

2.1 Overview

Search is an essential part of AI, appearing in many different flavours like A* search, hill climbing, simulated annealing, constraint satisfaction, genetic algorithms, and many more. Many subareas of AI use search in their problem solving procedures. This assignment applies A* search to a maze problem.

The maze problem we are dealing with in this assignment is finding a path through a maze, given a start position and a goal position in the maze. Implement the A* algorithm in Prolog with two different heuristics, test each of them with several examples, and compare the results. Instead of implementing the A* algorithm from scratch, you can use Bratko's code for the A* algorithm.

2.2 Datastructure

A maze can be viewed as a two-dimensional structure consisting of walls and paths. The easiest representation of such mazes in Prolog is a nested list structure. However, accessing an item in a list structure (i.e., a position in the maze) is not very efficient, since it takes time proportional to the length of the list. An array structure, which enable direct access to a required item, would be more suitable.

There is no array facility in Prolog, but arrays can be simulated very easily by using the built-in predicate `arg/3`. A goal `arg(N, Term, A)` is true if A is the Nth argument in Term. In our case, Term has a two-dimensional structure, such as `my(mx(...), mx(...), ...)`. Inside the inner terms, you could use the atoms `w` and `p` to indicate walls and paths, respectively. To state that this structure is a maze, you could put the following into your database:

